

- Note:
- $\rho_1 \sim \rho_2 \Leftrightarrow \exists s$ intertwining isomorphism (fs^{-1}) (25)
 - $\dim V_1 = \dim V_2$ is not sufficient condition for equivalence of ρ_1 & ρ_2

Examples

- see homomorphisms $C_{2v} \rightarrow M^{3 \times 3}$ & $C_{2v} \rightarrow (\{1, -1\}, \circ)$ discussed before

$$\bullet C_i = \{\epsilon, i\}, \rho: C_i \rightarrow \text{Aut}(R)$$

$$1, \rho_g(\epsilon) = \rho_g(i) = 1 \quad g \leftrightarrow \text{"gerade"}$$

$$2, \rho_u(\epsilon) = 1, \rho_u(i) = -1 \quad \text{"ungerade"}$$

Theorem 11: Let two matrix representations D and \tilde{D} of a group G be connected by a similarity transformation,

$$\tilde{D}(g) = B D(g) B^{-1} \quad \forall g \in G.$$

Then $D \sim \tilde{D}$.

Proof: • let's study basis transformation:

$$\bullet T(g) e_i = e_a D(g)_i^a \Rightarrow x'^k = D(g)_i^k x^i$$

$$\bullet \text{basis transformation: } \hat{e}_i = e_j A_i^j \Leftrightarrow e_j = \hat{e}_i (\tilde{A}^{-1})_i^j$$

$A: V \rightarrow V$... transformation matrix, $\det A \neq 0$

$$x = \hat{e}_i \hat{x}^i = e_j x^j - \hat{e}_i (\tilde{A}^{-1})_j^i x^j \Rightarrow \hat{x}^i = (\tilde{A}^{-1})_j^i x^j = B_j^i x^j$$

$$\Rightarrow \boxed{\hat{x} = B x}$$

- $e_i \hookrightarrow$ repre $D(g)$: $x' = D(g)x$
- $\hat{e}_i \hookrightarrow$ repre $\tilde{D}(g)$: $\hat{x}' = \tilde{D}(g)\hat{x}$ & $\hat{x}' = B x'$ for $\hat{x} = B x$

$$\hat{x}' = \tilde{D}(g)\hat{x} = \tilde{D}(g)Bx = Bx' = BD(g)x = \underbrace{BD(g)}_{B} \underbrace{B^{-1}x'}_{x'}$$

$$\Rightarrow \boxed{\tilde{D}(g) = BD(g)B^{-1}}$$

- $A = B^{-1}$ defines isomorphism $V \rightarrow V \Rightarrow D$ & \tilde{D} are equivalent

□

REDUCIBLE & IRREDUCIBLE REPRESENTATIONS

Def: Let $\phi: G \times V \rightarrow V$ be an action of a group G on a vect. space V and let $W \subset V$ is preserved under the action, that is,

$$T(g)w \in W \quad \forall g \in G \quad \forall w \in W \quad (G \cdot W \subset W)$$

Then the subspace $W \subset V$ is called invariant.

Def: Inv. subspace W is called irreducible if it does not contain any other non-trivial invariant subspace.

Def: Let V contains an invariant subspace under the group action defined by a repres. (\mathcal{G}, V) .

Then the vect. space V is called reducible and (\mathcal{G}, V) is reducible representation.

Representation, that is not reducible is called irreducible.

Def: A subrepresentation of a representation (\mathcal{G}, V) is a representation (\mathcal{G}_W, W) , where $W \subset V$ invariant subspace under the group action def. by (\mathcal{G}, V) .

Reducible matrix representations

- let $W \subset V$ be an invariant subspace \Rightarrow consider basis

$$W = \text{span}(e_1, \dots, e_r)$$

span ... linear span

$$W^\perp = V \setminus W = \text{span}(e_{r+1}, \dots, e_d)$$

| ... complement

- W invariant $\Rightarrow T(g) e_i = \sum_{k=1}^r e_k D(g)_{i,k}^k = \sum_k e_k D^W(g)_{i,k}^k$

$$\Rightarrow D(g) = \left(\begin{array}{c|c} D^W(g) & D^{W^\perp}(g) \\ \hline 0 & D^{W^\perp}(g) \end{array} \right) \quad (*)$$

- $D^W(g)$ forms a subrep of $D(G)$:

$$D(g_1)D(g_2) = \left(\begin{array}{c|c} D^W(g_1)D^W(g_2) & \dots \text{exercise} \dots \\ \hline 0 & D^{W^\perp}(g_1)D^{W^\perp}(g_2) \end{array} \right)$$

- $D^{W^\perp}(g)$ is also rep of G , but it is not (in general) subrep of G ... W^\perp needs not be invariant

NOTE: in an arbitrary basis of V , which does not conform to the structure of invariant subspaces, the matrices $D(g)$ do not have the block structure

(*)

- however, \exists similarity transform which will convert $D(g)$ to this form $\forall g \in G$ //

Def: Matrix representation is said to be reducible if it is equivalent to a matrix repel $D(g)$, in which the matrices have block structure (*) $\forall g \in G$.

Examples

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a, 2-dim repre of $G(\mathbb{R}^+, \cdot)$

- $(\mathbb{R}^+, \cdot) \sim (\mathbb{R}, +)$: $x = e^y \quad \cdot x \in (\mathbb{R}^+, \cdot), y \in (\mathbb{R}, +)$
 $xx' = e^{y+y'}; y = \log(x)$

$$\rightarrow D(x) = \begin{pmatrix} 1 & y \\ 0 & 1 \end{pmatrix} : D(x)D(x') = \begin{pmatrix} 1 & y+y' \\ 0 & 1 \end{pmatrix} = D(x+x')$$

- $D(x)$ is reducible; $W = \text{span}\left\{\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right\}$

$D|_W(x) = 1 \neq \dots$ deriv. representation

b, 3-dim repre of $\text{SO}(2)$

- action of $\text{SO}(2)$ on \mathbb{R}^3 : $T(g)v = R_\varphi^z v$

$$\begin{aligned} G \cdot \text{span}(e_z) &= \text{span}(e_z) = W_1, \\ G \cdot \text{span}(\{e_x, e_y\}) &= \text{span}(\{e_x, e_y\}) = W_2 \end{aligned} \quad \left. \begin{array}{l} \text{both invariant} \\ \} \end{array} \right.$$

$$R_\varphi^z = \begin{pmatrix} \cos \varphi & -\sin \varphi & 0 \\ \sin \varphi & \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{array}{l} \xrightarrow{R_\varphi^z \downarrow W_1 = 1 \dots \text{deriv. repre}} \\ \xrightarrow{R_\varphi^z \downarrow W_2 = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \dots \text{faithful 2D repre}} \end{array}$$

- $T(g) = R_\varphi^z \Rightarrow$ different decomposition to inv. subspaces
 $(\{e_x\} \cup \{e_y, e_z\})$

Def: Repr. (G, V) of a group G is called completely reducible if the repr. space V is a direct sum of irreducible invariant subspaces, $V = \bigoplus_i V_i$, under the group action

- direct sum of vect. spaces:

$$V = U \cup W \text{ & } U \cap W = \{0\} \Rightarrow V = U \oplus W$$

$\Rightarrow v = u + w$ is unique decomposition, $u \in U$ & $w \in W$

in an appropriate basis complying with the decomposition (29) the matrices of the representation have block-diag. form

$$D(g) = \begin{pmatrix} D^1(g) & & 0 \\ & D^2(g) & \\ 0 & & \ddots D^k(g) \end{pmatrix} \equiv \text{diag}(D^1(g), D^2(g), \dots, D^k(g)) \\ \equiv \bigoplus_i D^i(g)$$

$\rightarrow D^i(g)$ are irreducible repre

Def. Matrix repre $D(g)$ is completely reducible if it is equivalent to a repre $D'(g)$ of block-diagonal matrices $\forall g \in G$.

Example:

• $SO(2)$ on \mathbb{R}^2 is completely reducible after generalization to complex space:

$$\xi_1 = e_x + i e_y \quad \xi_2 = e_x - i e_y \quad \text{generate } \mathbb{C}\text{-invariant}$$

subspaces:

$$\begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} 1 \\ i \end{pmatrix} = e^{-i\varphi} \begin{pmatrix} 1 \\ i \end{pmatrix}, \dots$$

NOTE (later): complex irreduc. repre of an abelian gr. are 1D

$$A = \frac{i}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \Rightarrow A^+ \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} A = \begin{pmatrix} e^{-i\varphi} & 0 \\ 0 & e^{i\varphi} \end{pmatrix}$$

$\rightarrow e^{-i\varphi}$ & $e^{i\varphi}$ are two non-equiv. faithful 1D repre

• $D(x) = \begin{pmatrix} 1 & y \\ 0 & 1 \end{pmatrix}$ as a repre of $(\mathbb{R}^+, \cdot) \cong (\mathbb{R}, +)$ is not completely reducible:

Let $\exists A : \begin{pmatrix} 1 & y \\ 0 & 1 \end{pmatrix} = A \begin{pmatrix} f(y) & 0 \\ 0 & g(y) \end{pmatrix} A^{-1} \Rightarrow \text{det \& Tr are invariant under similarity transf} \Leftrightarrow f(y)g(y) = 1$
 $f(y) + g(y) = 2$

$$\Rightarrow f(y) = g(y) = 1 \quad \forall y \text{ (indep. of } y)$$

Theorem XII

Any irreducible representation of a finite group is finite-dimensional.

Proof: • (\mathcal{G}, V) is irrep, $x \in V$ arbitrary

$\mathcal{G} \cdot x = \{T(g)x \mid g \in \mathcal{G}\}$ is finite-dim set of vectors from V

$\Rightarrow \text{span}(\mathcal{G} \cdot x) \subset V$ is finite-dim invar. subspace of V

• (\mathcal{G}, V) irrep $\Rightarrow \text{span}(\mathcal{G} \cdot x) = V \Rightarrow \dim V < +\infty \quad \square$

UNITARY REPRESENTATIONS

<1>

- Hilbert space: • vect. space \mathcal{H} with an inner (dot) product
- it is complete with respect to the metric induced by the inner product
(Cauchy sequence is convergent within \mathcal{H})
- it is separable (each $y \in \mathcal{H}$ is a limit of some sequence from a countable subset $M \subset \mathcal{H}$ (\Rightarrow f countable basis))

unitary operators:

- for bounded operators ($\exists K \in \mathbb{R} : \|U\varphi\| \leq K\|\varphi\| \quad \forall \varphi \in \mathcal{H}$) it is possible to define conjugation:

$$\langle \varphi | A^+ \varphi \rangle = \langle A\varphi | \varphi \rangle \quad \forall \varphi \in \mathcal{H}$$

- then for invertible bounded ops we can define unitarity:

$$\begin{aligned} \langle \varphi | \varphi \rangle &= \langle U\varphi | U\varphi \rangle = \langle \varphi | U^+U\varphi \rangle \quad \forall \varphi \in \mathcal{H} \\ \Leftrightarrow U^+U &= \mathbb{1} \quad \& \exists U^{-1} \Rightarrow U^{-1} = U^+ \Rightarrow UU^+ = \mathbb{1} \end{aligned}$$

Def: Unitary repres of \mathcal{G} is a repres on a Hilbert space \mathcal{H} such that every $g \in \mathcal{G}$ is represented by an unitary operator $U(g)$:

$$U(g)^+U(g) = U(g)U(g)^+ = \mathbb{1} \quad (\Leftrightarrow \langle U(g)\varphi | U(g)\varphi \rangle = \langle \varphi | \varphi \rangle \quad \forall g \in \mathcal{G} \quad \& \quad \forall \varphi \in \mathcal{H})$$

Def: Matrix unitary repres is such that every element $g \in G$ is represented by an unitary matrix

$$D(g)^{-1} = D(g)^+$$

Theorem XIII

Every finite-dimensional reducible unitary repres (ρ, \mathcal{H}) of a group G is completely reducible.

Proof: • ρ reducible $\Rightarrow \exists \mathcal{H}_1 \subset \mathcal{H}$ nontriv. inv. subspace

$\Rightarrow \mathcal{H}_1^\perp = \mathcal{H} | \mathcal{H}_1$ is also invariant:

- $\psi \in \mathcal{H}_1^\perp \Rightarrow \langle \psi | \psi \rangle = 0 \quad \forall \psi \in \mathcal{H}_1$

- $U(g)\psi \in \mathcal{H}_1^\perp : \langle \psi | U(g)\psi \rangle = \langle U(g)U(g)^\dagger\psi | U(g)\psi \rangle$

$$= \langle U(g^{-1})\psi | U(g)^\dagger U(g)\psi \rangle = \langle \psi | \psi \rangle = 0$$

\mathcal{H}_1 inv. $\Rightarrow U(g^{-1})\psi \in \mathcal{H}_1$

- if \mathcal{H}_1 or \mathcal{H}_1^\perp are further reducible then the same decomposition can be repeated until complete reducibility ... provided $\dim \mathcal{H} < +\infty$

□

Note: ZD-repres (\mathbb{R}^+, \circ) is not unitary \Rightarrow Th. does not apply

Theorem XIV

Every finite-dim representation of a finite or compact Lie group is equivalent to some unitary representation.

NB: we do not require the Repres space to be a Hilbert space!

Proof (hint):

- every finite-dim vect. space $\sim \mathbb{R}^n$ or \mathbb{C}^n
- \Rightarrow it is possible to select basis $\{\ell_1, \dots, \ell_n\}$

$$\Rightarrow x = x^i \ell_i \quad \forall x \in V$$

$\Rightarrow \langle x | y \rangle \equiv (x^i)^* y^i$ is a legal inner product:

- $\cdot \langle x | y \rangle = \langle y | x \rangle^*$ (conjugate sym.)
- linear in first argument
- $\cdot \langle x | x \rangle > 0 \quad \forall x \in V \setminus \{0\}$ (positive definite)

- if (S, V) is not unitary with resp. to $\langle \cdot | \cdot \rangle$, it is possible to construct another inner product

$$\langle x | y \rangle = \frac{1}{\#G} \sum_{g'} \langle T(g)x | T(g)y \rangle$$

$$\Rightarrow / \text{rearr. theorem} / \Rightarrow \langle T(g)x | T(g)y \rangle = \langle x | y \rangle$$

$\Rightarrow (S, V)$ is unitary with resp. to $\langle \cdot | \cdot \rangle$

□

Note: • $\langle \cdot | \cdot \rangle$ is equivalent to $\langle \cdot | \cdot \rangle$ - induces equal topology
(i.e., open sets on V) \Leftrightarrow the same convergent sequences

$$\Leftrightarrow \exists a, b \in \mathbb{R}, 0 < a \leq b : a \langle x | x \rangle \leq \langle x | x \rangle \leq b \langle x | x \rangle \quad \forall x \in V$$

- compact Lie groups = compact smooth manifolds
 \equiv parameterized by coordinates from a compact
subspace of \mathbb{R}^n if \exists global map;
(compact set in \mathbb{R}^n : closed & bounded)

- $SO(2), O(n)$ are compact, (\mathbb{R}^+, \cdot) is not

- for comp. Lie groups \exists left-invariant measure

$$\exists \int_G dg < +\infty : \int_G f(hg) dg = \int_G f(g) dg \Rightarrow \frac{1}{\#G} \sum_{g'} \rightarrow \frac{1}{|G|} \int_G dg$$

Theorem XV (Maschke)

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Every finite-dim. reducible repn of a finite (compact Lie) group is completely reducible.

Proof: • combine Th XIV 2 + XIII

□

SCHUR'S LEMMA

Lemma SC1:

Let (ρ_1, V_1) and (ρ_2, V_2) be irreducible repns of a group G & let S is the intertwining mapping

$$S: V_1 \rightarrow V_2 \quad S T_1(g) v_1 = T_2(g) S v_1 \quad \forall g \in G \quad \forall v_1 \in V_1$$

Then either $S = 0$ ($\Leftrightarrow \text{Ker } S = V_1$) or S is isomorphic map $\Rightarrow \rho_1 \cong \rho_2$.

Proof: • $\text{Ker } S$ & $\text{Im } S$ are invariant subspaces of V_1 & V_2 , resp:

$$\text{a, } v_1 \in \text{Ker } S \Rightarrow S T_1(g) v_1 = T_2(g) S v_1 = 0 \Rightarrow T_1(g) v_1 \in \text{Ker } S$$

$$\text{b, } v_2 \in \text{Im } S \Rightarrow \exists v_1 \in V_1 : v_2 = S v_1$$

$$\Rightarrow T_2(g) v_2 = T_2(g) S v_1 = S T_1(g) v_1 = S v_1' \Rightarrow T_1(g) v_1' \in \text{Im } S$$

• V_1 & V_2 are irreducible \Rightarrow there are only 2 options:

$$\text{a, } \text{Ker } S = V_1 \text{ & } \text{Im } S = \{0\} \Leftrightarrow S = 0$$

$$\text{b, } \text{Im } S = V_2 \text{ & } \text{Ker } S = \{0\} \Rightarrow S \text{ is bijective:}$$

• surjective by $\text{Im } S = V_2$

$$\cdot \text{ injective: } S v_1 = S v_1' = v_2 \Rightarrow S(v_1 - v_1') = 0$$

$$\Rightarrow v_1 - v_1' \in \text{Ker } S \Rightarrow v_1 - v_1' = 0$$

□

Lemma SL2 (consequence of SL1 for finite-dim irreps) (34)

Let (ρ, V) be a complex finite-dim irreducible rep of a group G and S is intertwining operator on V ($S: V \rightarrow V$) such that

$$T(g)Sv = ST(g)v \quad \forall g \in G \quad \forall v \in V.$$

Then $S = \lambda \mathbb{1}$ for some $\lambda \in \mathbb{C}$.

Proof: • let $S \neq 0 \Rightarrow \exists \lambda \in \mathbb{C} \exists v \in V: S_{v_\lambda} = \lambda v_\lambda$
(in a finite dim there always exists a solution
of a characteristic polynomial in $\mathbb{C} \Rightarrow$ every
operator has an eigenvalue)

• eigen-subspace $V_\lambda \subset V$ corresponding to λ
is invariant under the action of G :

$$v \in V_\lambda \Rightarrow ST(g)v = T(g)Sv = \lambda T(g)v \Rightarrow T(g)v \in V_\lambda$$

$$\Rightarrow /(\rho, V) \text{ irred.} / \Rightarrow V_\lambda = V \Rightarrow S = \lambda \mathbb{1} \quad (Se_i = \lambda e_i \quad \forall e_i \in \text{basis})$$

Note: • in an infinite-dim V the subspace V_λ need not
to be closed:
 $\{v_n\} \subset V_\lambda$ Cauchy sequence in V_λ does not

imply $\lim_{n \rightarrow \infty} v_n = v \in V_\lambda \Rightarrow ST(g) = T(g)S$

does not imply invariance of V_λ

CONSEQUENCES OF SCHUR LEMMAS

(35)

Theorem XVI

Complex finite-dim irreducible representations of an Abelian group are one-dimensional.

Proof: • (ρ, V) finite-dim, G Abelian \Rightarrow

$$\rho(g)\rho(h) = \rho(h)\rho(g) \quad \forall g, h \in G$$

$$\xrightarrow{(\text{SCH})} \rho(h) = \lambda(h) \mathbb{I} \quad \forall h \in G$$

$\Rightarrow \rho$ is either reducible or 1-dim. \square

Note: $SO(2)$ is Abelian but we had to move into complex repespace to obtain 1-dim irreps.

Theorem XVII (Orthogonality relations for matrix representations)

Let D^α and D^ν are two unitary irreducible matrix repes of a finite (compact Lie) group. Dimensions of the representations are d_μ & d_ν , resp. Let D^α and D^ν are not equivalent for $\mu \neq \nu$ or identical for $\mu = \nu$. Then

$$\sum_g [D^\alpha(g)^*]_i^j D^\nu(g)_\ell^\kappa = \frac{\#G}{d_\mu} \delta_{\mu\nu} \delta_{ij} \delta_{\ell\kappa} \quad (*)$$

Proof: • B is an arbitrary $d_\mu \times d_\nu$ matrix

$$\Rightarrow A = \sum_g D^\alpha(g^{-1}) B D^\nu(g) \Rightarrow D^\alpha(h) A = A D^\nu(h) \quad \forall h \in G:$$

$$\sum_g D^\alpha(h) D^\alpha(g^{-1}) B D^\nu(g) = / h \bar{g}^{-1} = g^{-1} \Rightarrow g = gh^{-1} \text{ & rewr. theorem/}$$

$$= \sum_{g'} D^\alpha(g') B D^\nu(g'h) = A D^\nu(h)$$

1, D^{μ} not equiv to $D^{\nu} \Rightarrow /S\subset Z/ \Rightarrow A = 0$ & choose

$$B_k^j = \delta_{jr} \delta_{ks} \text{ for a fixed } r, s$$

$$\Rightarrow 0 = \sum_{j \in G} \sum_g D^{\mu}(g^{-1})_j^i \delta_{jr} \delta_{ks} D^{\nu}(g)_k^s = \sum_g D^{\mu}(g^{-1})_r^i D^{\nu}(g)_k^s$$

$$\boxed{0 = \sum_g (D^{\mu}(g)_r^i)^* D^{\nu}(g)_k^s \text{ for } \mu \neq \nu}$$

2, $D^{\mu} \sim D^{\nu} \Rightarrow \exists S: D^{\nu}(g) = S D^{\mu}(g) S^{-1}$

$$\Rightarrow D^{\mu}(h) A = A S D^{\mu}(h) S^{-1} \rightarrow D^{\mu}(h) A S = A S D^{\mu}(h)$$

$$\Rightarrow /S \subset Z/ \Rightarrow A S = \lambda \mathbb{1}_{\partial \mu + \partial \mu}$$

$$\cdot \lambda \text{ from } \text{Tr}: \text{Tr}(AS) = \text{Tr}(\lambda) = \text{Tr}\left(\sum_g D^{\mu}(g^{-1}) B S D^{\mu}(g) S^{-1}\right)$$

$$\Rightarrow \lambda = \frac{\#G}{\#\mu} \text{Tr}(BS) = /B_k^j = \delta_{jr} \delta_{ks} / = \frac{\#G}{\#\mu} B_k^j S_r^s$$

$$\Rightarrow \boxed{\lambda = \frac{\#G}{\#\mu} S_r^s}$$

$$\cdot A_k^i = \lambda (S^{-1})_k^i = \sum_{j \in G} \sum_g D^{\mu}(g)_j^i \delta_{jr} \delta_{ks} D^{\nu}(g)_k^s$$

$$\Rightarrow \sum_g (D^{\mu}(g)_r^i)^* D^{\nu}(g)_k^s = \frac{\#G}{\#\mu} S_r^s (S^{-1})_k^i$$

$$3, \mu = \nu \Rightarrow S_r^s = (S^{-1})_k^i = \delta_{ik}$$

$$\Rightarrow \sum_g (D^{\mu}(g)_r^i)^* D^{\nu}(g)_k^s = \frac{\#G}{\#\mu} \delta_{ur} \delta_{sr} \delta_{il} \quad \square$$

Direct consequence: $\sum_{\mu} \#\mu \leq \#G$:

(*) is orthogonality relation between $\#G$ -dim vectors $(D^{\mu}(g_1)_j^i, \dots, D^{\mu}(g_{\#G})_j^i)$, which are indexed by (μ, i, j)
 \Rightarrow total number of these orthog. vectors is $\sum_{\mu} \#\mu$ & must be $\leq \#G$