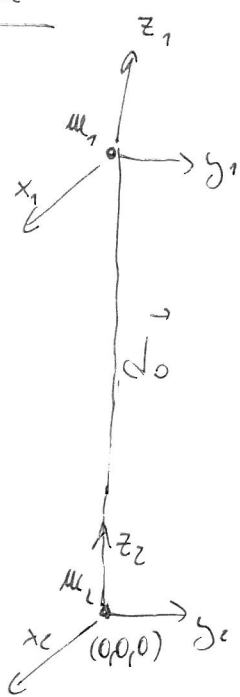


dimer

(1)



1, Hamiltonian  
 $d_0 = d_0 \vec{e}_z$

$$\vec{d} = (x_1 - x_2) \vec{e}_x + (y_1 - y_2) \vec{e}_y + (d_0 + z_1 - z_2) \vec{e}_z$$

$$V = \frac{1}{2} k (d_0 - |\vec{d}|)^2$$

$$|\vec{d}| = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (d_0 + z_1 - z_2)^2}$$

$$\approx \left[ x_i \ll d_0 \right] = d_0 \sqrt{\frac{(x_1 - x_2)^2}{d_0^2} + \frac{(y_1 - y_2)^2}{d_0^2} + \left(1 + \frac{z_1 - z_2}{d_0}\right)^2}$$

$$= d_0 \sqrt{1 + 2 \frac{z_1 - z_2}{d_0} + \frac{(x_1 - x_2)^2}{d_0^2} + \frac{(y_1 - y_2)^2}{d_0^2}}$$

$$= d_0 + (z_1 - z_2) + O\left(\frac{(x_1 - x_2)^2}{d_0}\right)$$

$$\Rightarrow V \sim \frac{1}{2} k (z_1 - z_2)^2$$

$$z_1 = \frac{q_3}{\sqrt{m_1}} \quad z_2 = \frac{q_6}{\sqrt{m_2}} \Rightarrow V = \frac{1}{2} k \left( \frac{q_3}{\sqrt{m_1}} - \frac{q_6}{\sqrt{m_2}} \right)^2$$

$$\Rightarrow V = \frac{1}{2} k \left[ q_3^2 \frac{1}{m_1} + q_6^2 \frac{1}{m_2} - 2 \frac{q_3 q_6}{\sqrt{m_1 m_2}} \right]$$

$$\Rightarrow B = \frac{1}{2} k \begin{pmatrix} \frac{1}{m_1} & -\frac{1}{\sqrt{m_1 m_2}} \\ -\frac{1}{\sqrt{m_1 m_2}} & \frac{1}{m_2} \end{pmatrix}$$

2, diagonalization:  $\left(\frac{1}{m_1} - \lambda\right)\left(\frac{1}{m_2} - \lambda\right) - \frac{1}{m_1 m_2} = \frac{1}{m_1 m_2} - \lambda \left(\frac{1}{m_1} + \frac{1}{m_2}\right) + \lambda^2 - \frac{1}{m_1 m_2} = 0 \Rightarrow \lambda \left(\lambda - \frac{m_1 + m_2}{m_1 m_2}\right) = 0$

$$\Rightarrow \lambda_1 = 0 \quad \dots \text{translation}$$

$$\lambda_2 = \frac{m_1 + m_2}{m_1 m_2} \cdot \frac{1}{2} k \quad \dots \text{vibrations}$$

$$\Leftrightarrow Q_{tr} = q_3 \sqrt{\frac{m_1}{m_1+m_2}} + q_6 \sqrt{\frac{m_2}{m_1+m_2}} \quad \dots \text{translation} \quad (1)$$

$$Q_{vib} = q_3 \sqrt{\frac{m_2}{m_1+m_2}} - q_6 \sqrt{\frac{m_1}{m_1+m_2}} \quad \dots \text{vibration} \quad (2)$$

Note:  $Q_{tr} \neq (q_3, q_6)$

$$q_i = x_i \sqrt{m_i} \Rightarrow Q_{tr} = z_1 \frac{m_1}{\sqrt{m_1+m_2}} + z_2 \frac{m_2}{\sqrt{m_1+m_2}}$$

$\Rightarrow$  it is not even  $(z_1, z_2)$  which would be "natural" as it is translation  $\Rightarrow$  both atoms move by the same distance

3, Inversion:

$$a, \sqrt{m_1}(1) + \sqrt{m_2}(2) \Rightarrow Q_{tr} \sqrt{m_1} + Q_{vib} \sqrt{m_2} = q_3 \frac{m_1+m_2}{\sqrt{m_1+m_2}}$$

$$\Rightarrow q_3 = \frac{1}{\sqrt{m_1+m_2}} (Q_{tr} \sqrt{m_1} + Q_{vib} \sqrt{m_2}) \quad z_1 = \frac{q_3}{\sqrt{m_1}}$$

$$\Rightarrow z_1 = \frac{1}{\sqrt{m_1+m_2}} \left( Q_{tr} + Q_{vib} \sqrt{\frac{m_2}{m_1}} \right)$$

$$b, \sqrt{m_2}(1) - \sqrt{m_1}(2) \Rightarrow Q_{tr} \sqrt{m_2} - Q_{vib} \sqrt{m_1} = q_6 \frac{m_1+m_2}{\sqrt{m_1+m_2}}$$

$$\Rightarrow q_6 = \frac{1}{\sqrt{m_1+m_2}} (Q_{tr} \sqrt{m_2} - Q_{vib} \sqrt{m_1})$$

$$\Rightarrow z_2 = \frac{1}{\sqrt{m_1+m_2}} \left( Q_{tr} - Q_{vib} \sqrt{\frac{m_1}{m_2}} \right)$$

$\Rightarrow$  only now we see the meaning of  $Q_{tr}$  vs  $Q_{vib}$ :

$Q_{vib} = 0 \Rightarrow z_1 = z_2$  &  $Q_{tr}$  indeed corresponds to translation without deformation

$Q_{tr} = 0 \Rightarrow \frac{z_1}{z_2} = -\frac{m_2}{m_1}$  meaning center of mass does not move!

- note that it is not trivial to guess normal coordinates and, in particular, obtain the internal ones by "subtraction" of translations & rotations as these are nontrivial due to the "mass scaling" (3)

