

RELATIONS BETWEEN REPRESENTATIONS OF A GROUP & ITS SUBGROUPS

A, SUBDUCED REPRESENTATIONS

Def: Let $T(g)$ be operators of a repre (ρ, V) of G and let $H < G$ is a subgroup. Then

$$\rho \downarrow H = \{T(h) \mid h \in H\}$$

forms subduced representation of H

• $\rho \downarrow H$ in general reducible even for ρ IRREP of G

$$\rho \downarrow H = \bigoplus_{\mu} \alpha_{\mu} \rho_{\mu} \downarrow H \Leftrightarrow \alpha_{\mu} = \frac{1}{\#H} \sum_{h \in H} \chi_{\mu}(h)^* \chi(h)$$

Example: • $H = C_s = \{E, \sigma_v\} < G = C_{3v} = \{E, 2C_3, 3\sigma_v\}$

C_{3v}	E	$2C_3$	$3\sigma_v$	
A_1	1	1	1	$\rightarrow A_1 \downarrow C_s = A'$
A_2	1	1	-1	$\rightarrow A_2 \downarrow C_s = A''$
E	2	-1	0	$\rightarrow E \downarrow C_s = A' \oplus A''$
C_s	E	σ_v		
A'	1	1		
A''	1	-1		

B, INDUCED REPRESENTATIONS (For finite groups)

• let $H < G$ & $D_H(h)$ is a d -dim. repre of H

\Rightarrow can we construct a repre of the full G ?

YES, by explicit construction of its basis!

1, decomposition of G into left cosets with resp. to H

$$G = p_1 H + p_2 H + \dots + p_M H \quad M = \frac{\#G}{\#H} \quad (\text{Lagrange})$$

- p_i fixed representatives of individual classes
- $p_1 = e$

2, basis of the induced repre of G

• let $\{\phi_1, \dots, \phi_d\}$ be the basis of D_H

$$\Rightarrow T(h)\phi_i = \sum_{j=1}^d \phi_j \cdot D_H(h)_i^j$$

repre space of D_H

$\text{span}\{\phi_{ti}\} = \bigoplus_{t=1}^M p_t V_H$

isomorphic copy of V_H

• def. $\phi_{ti} \equiv T(p_t)\phi_i \quad t=1, \dots, M; i=1, \dots, d$

(they are abstract objects not living in the repre space of D_H , we don't really know what they are...)

$\Rightarrow \phi_{ti}$ forms a basis of dM -dim repre of G

(we will not prove they are lin. indep.):

$$T(g)\phi_{ti} = T(gp_t)\phi_i = T(p_s p_s^{-1} g p_t)\phi_i = T(p_s)T(p_s^{-1} g p_t)\phi_i$$

- p_s : $p_s^{-1} g p_t \in H \Leftrightarrow g p_t \in p_s H$
- (such p_s exists and is unique because $g p_t = g' \in G$ and each element of G belongs to exactly one coset)

$$\Rightarrow T(g)\phi_{ti} = T(p_s) \sum_j \phi_j D_H(p_s^{-1} g p_t)_i^j = \sum_j \phi_{sj} D_H(p_s^{-1} g p_t)_i^j$$

for $g p_t \in p_s H$

• def. $\delta_{st}(g) = \begin{cases} 1 & g p_t \in p_s H \\ 0 & g p_t \notin p_s H \end{cases}$

$\Rightarrow D_G(g)_{ti}^{sj} = \delta_{st}(g) D_H(p_s^{-1} g p_t)_i^j$

induced repre of G

$D_G = D_H \uparrow G$

• note that we don't really know what $T(P_t) \phi_i$ is
but we don't need to in the end...

(5)

3, $D_G(g)_{\epsilon_i}^{sj}$ is indeed a repere

$$a, g = e \Rightarrow \delta_{st}(e) = \delta_{st} : e P_\epsilon = P_\epsilon \in P_\epsilon H$$

$$\Rightarrow D_H(P_s^{-1} g P_\epsilon) = D_H(P_\epsilon^{-1} e P_\epsilon) = D_H(e) = \mathbb{1}$$

$$\Rightarrow D_G(e) = \mathbb{1}_{\dim \times \dim}$$

$$b, \sum_{rk} D_G(g)_{rk}^{sj} D_G(g')_{\epsilon_i}^{rk} = \sum_{rk} \delta_{sr}(g) \delta_{r\epsilon}(g') D_H(P_s^{-1} g P_r)_k^j D_H(P_r^{-1} g' P_\epsilon)_i^k$$

← this selects one unique r from the Σ_r

$$= / g P_r = P_s h \ \& \ g' P_\epsilon = P_r h' \Rightarrow g g' P_\epsilon = g P_r h' = P_s h h' \Rightarrow \delta_{st}(g g')$$

& $\exists!$ P_r such that $g P_r \in P_s H \Rightarrow$ sum over r gives just single nonzero contrib.

$$= \delta_{st}(g g') D_H(P_s^{-1} g g' P_\epsilon)_i^j \quad \square$$

Theorem: D_H unitary $\Rightarrow D_{G \uparrow H}$ unitary

$$\text{Proof: } [D_G(g)^{-1}]_{\epsilon_i}^{sj} = [D_G(g^{-1})]_{\epsilon_i}^{sj} = \delta_{st}(g^{-1}) D_H(P_\epsilon^{-1} g^{-1} P_\epsilon)_i^j$$

$$= / g^{-1} P_\epsilon = P_s h \Leftrightarrow g P_s = P_\epsilon h' \Rightarrow \delta_{st}(g^{-1}) = \delta_{\epsilon s}(g) /$$

$$= \delta_{\epsilon s}(g) D_H((P_\epsilon^{-1} g P_s)^{-1})_i^j = / \text{unitarity} / = \delta_{\epsilon s}(g) [D_H(P_\epsilon^{-1} g P_s)_j^i]^*$$

$$= [D_G(g)^+]_{\epsilon_i}^{sj} \quad \square$$

• character of an induced repre

$$\chi_G(g) = \sum_{s_j} \delta_{ss}(g) D_H(P_s^{-1} g P_s)_j = \sum_s \delta_{ss}(g) \chi_H(P_s^{-1} g P_s)$$

\uparrow
H

• summation over M selected elements P_s can be replaced by a sum over $\forall g' \in G$ with additional condition $g'^{-1} g g' \in H \Rightarrow$ instead of a single representative of each coset we take every element from the coset, i.e., $\#H$ equal contributions instead of 1:

$$g P_s \in P_s H \quad (\delta_{ss}(g)) \quad \& \quad g' \in P_s H \Rightarrow g'^{-1} g g' = (P_s h')^{-1} g (P_s h) \\ = h'^{-1} P_s^{-1} g P_s h' = h'^{-1} h h' \in H \Rightarrow g g' \in g' H = P_s H$$

$$\Rightarrow \chi_G(g) = \sum_s \delta_{ss}(g) \chi_H(P_s^{-1} g P_s) = \frac{1}{\#H} \sum_{\substack{g' \\ g'^{-1} g g' \in H}} \chi_H(g'^{-1} g g')$$

• both expressions useful - in different situations

• decomposition of $D_{H \uparrow G} = D_G$

- assume we are inducing IRREP of H : $\rho_G^{\uparrow G}$ is a repre of G induced from the $\rho_H^{\downarrow H}$ IRREP of H :

$$\rho_G^{\uparrow G} = \bigoplus_{\mu} \alpha_{\mu}^{\uparrow G} \rho_G^{\mu}$$

$$\rho_H^{\downarrow H} = \bigoplus_{\nu} \alpha_{\nu}^{\downarrow H} \rho_H^{\nu}$$

Theorem XXV: (Frobenius)

$$\alpha_{\mu}^{\uparrow G} = \alpha_{\nu}^{\downarrow H}$$

in words: IRREP ρ^{μ} of G is contained in $\rho^{\nu \uparrow G}$ (60)

as many times as is the IRREP ρ_H^{ν} contained in $\rho^{\mu \downarrow H}$,

very easy to determine!

$$\rightarrow \chi_{\rho^{\nu \uparrow G}}(g) = \sum_{\mu} \alpha_{\mu}^{\nu \uparrow G} \chi_{\rho^{\mu}}(g) = \sum_{\mu} \alpha_{\nu}^{\mu \downarrow G} \chi_{\rho^{\mu}}(g)$$

Proof: $\alpha_{\mu}^{\nu \uparrow G} = \frac{1}{\#G} \sum_g \chi_{\rho^{\mu}}(g)^* \frac{1}{\#H} \sum_{\substack{g' \in G \\ g'^{-1} g g' \in H}} \chi_{\rho_H^{\nu}}(g'^{-1} g g') =$

$$= \frac{1}{\#G \#H} \sum_{h \in H} \chi_{\rho_H^{\nu}}(h) \sum_{g'} \chi_{\rho^{\mu}}(g' h g'^{-1})^* \quad \#G \times \text{the same!}$$

$$= \frac{1}{\#H} \sum_{h \in H} \chi_{\rho_H^{\nu}}(h) \chi_{\rho^{\mu}}(h)^* = (\alpha_{\nu}^{\mu \downarrow H})^* = \alpha_{\nu}^{\mu \downarrow H}$$



Examples: 1, $H = \{e\}$, D_H is trivial rep $\Rightarrow D_{H \uparrow G}$ is regular rep

SYMMETRIES IN QM

- G is a symmetry group of a system
($\Rightarrow \hat{H}$ (Schr. eq.) invariant with resp. to symmetry operations from G)
→ what does it mean?
→ how is the theory of repre useful?
- description of q . system - vector from Hilbert space \mathcal{H}
→ 1 spinless particle $\Rightarrow \psi \in L^2(\mathbb{R}^3)$ (bound states)
- action of G on $\mathcal{H} \Rightarrow$ typically \mathcal{D} -dim unitary representation
 $\rho: G \rightarrow ISO(\mathcal{H})$
- non-relativistic QM: G typically $O(3), SO(3)$, point groups, crystallographic groups

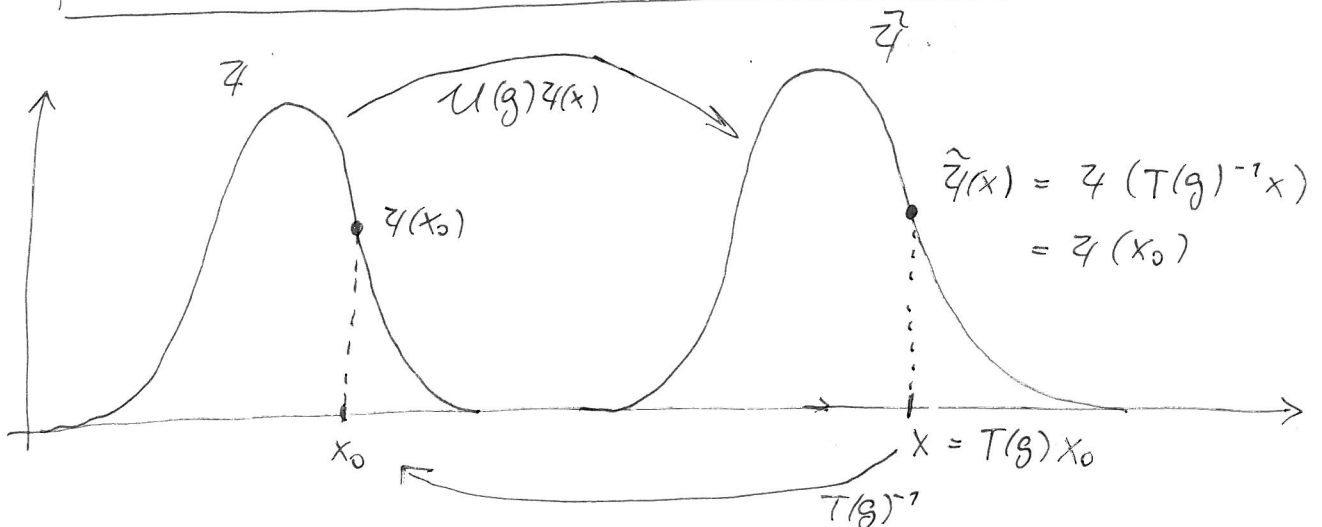
Action of G on $L^2(\mathbb{R}^3)$

1, action of G on \mathbb{R}^3 : $g \mapsto T(g) \in Aut(\mathbb{R}^3)$

$\boxed{x' = T(g)x}$... coordinate transformation

2, corresp. unitary op. $U(g) \in ISO(L^2(\mathbb{R}^3))$:

$\boxed{\tilde{\psi}(x) = U(g)\psi(x) \equiv \psi(T(g)^{-1}x) \quad \forall \psi \in L^2(\mathbb{R}^3)}$



• $U(g)$ is indeed a representation of G :

(53)

$$\begin{aligned}
 U(g_1)U(g_2)\psi(x) &= U(g_1)\psi(T(g_2)^{-1}x) = \psi(T(g_2)^{-1}T(g_1)^{-1}x) \\
 &\quad \uparrow \\
 &\quad \text{note the order, } T(g_1) \text{ acts directly on } x \\
 &= \psi([T(g_1)T(g_2)]^{-1}x) = \psi(T(g_1g_2)^{-1}x) = U(g_1g_2)\psi(x) \quad \square
 \end{aligned}$$

Transformation of operators

• $\psi \mapsto U(g)\psi \Rightarrow A \mapsto \tilde{A}$ such that matrix elements remain unchanged

\rightarrow this must hold for any $U(g)$ generated by coordinate transformation, regardless symmetry - shifting/rotating whole system in space can't change physics

$$\Rightarrow \langle \psi | A | \psi \rangle = \langle U(g)\psi | \tilde{A} | U(g)\psi \rangle$$

|| unitarity

$$\langle \psi | U(g)^\dagger \tilde{A} U(g) | \psi \rangle$$

$$\Rightarrow \boxed{\tilde{A} = U(g) A U(g)^\dagger}$$

• what does it mean in "x-representation"?

$$\begin{aligned}
 \phi(x) = A(x)\psi(x) &\xrightarrow{U(g)} \phi(T(g)^{-1}x) = A(T(g)^{-1}x)\psi(T(g)^{-1}x) \\
 U(g)A(x)\psi(x) &= A(T(g)^{-1}x)U(g)\psi(x) \\
 &= \tilde{A}(x)U(g)\psi(x)
 \end{aligned}$$

$$\Rightarrow \boxed{\tilde{A}(x) = U(g)A U(g)^\dagger = A(T(g)^{-1}x)}$$

Note: • multi-component ψ (bispinors, ...) ... individual components might mix under action of $G \Rightarrow$

$$U(g) \begin{pmatrix} \psi_1(x) \\ \vdots \\ \psi_n(x) \end{pmatrix} = D(g) \begin{pmatrix} \psi_1(T(g)^{-1}x) \\ \vdots \\ \psi_n(T(g)^{-1}x) \end{pmatrix} \quad \text{with } D(g) \text{ some } n\text{-dim. rep of } G$$

• Hamiltonian transformation

$$H \xrightarrow{g} U(g) H U(g)^\dagger$$

• $g \in G$ symmetry group of a system $\Leftrightarrow H$ invariant

$$\Rightarrow H U(g) = U(g) H \quad \forall g \in G$$

Note: • $U(g)$ is not from IRREP \Rightarrow does not imply $H = \lambda \mathbb{1}$
but ...

• eigenfunctions

$$H \psi = \lambda \psi \xrightarrow{g} U(g) H \psi \stackrel{[H,U]=0}{=} H U(g) \psi = \lambda U(g) \psi$$

\Rightarrow subspace $\mathcal{H}_\lambda \subset \mathcal{H}$ of eigenfunctions corresp. to (possibly degenerate) λ is invariant under action of G

\Rightarrow basis of \mathcal{H}_λ forms basis of a rep of G on \mathcal{H}_λ :

$$U(g) \psi_{\lambda, n} = \sum_m \psi_{\lambda, m} D^\lambda(g)_{m, n} \quad \text{span}(\{\psi_{\lambda, 1}, \dots, \psi_{\lambda, d}\}) = \mathcal{H}_\lambda$$

1, \mathcal{H}_λ does not contain proper invar. subspace

$\Rightarrow D^\lambda$ is IRREP & its dimension corresponds to the degree of degeneracy of λ
(note that indeed $H = \lambda \mathbb{1}$ on \mathcal{H}^λ as required by Schur)

\Rightarrow symmetry explains degeneracy of an energy level:

• if the eigenfunc. transforms as multi-dim IRREP then the level must be degenerate

• ground state typically totally sym \leftrightarrow trivial IRREP \Rightarrow non-degenerate

\Rightarrow this is normal/geometrical degeneracy

2, \mathcal{H}_1 reducible

a) accidental degeneracy

- due to specific values of some constants (ie, for specific geometry)

b) hidden (usually dynamical) symmetry

- true sym. group is larger \Rightarrow higher-dim. IRREPs

Examples: 1, hidden symmetry - H atom

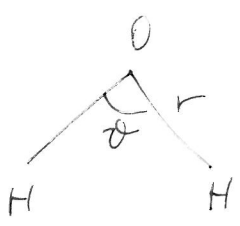
- apparent sym. group is $SO(3) \Rightarrow E_{nl} = E_n$ seems accidental
- additional symmetry - Laplace-Runge-Lenz vector (remember Kepler problem: $\vec{A} = \vec{p} \times \vec{L} - mk\vec{r}$)

$$A_q = -mk\hat{r}_q + \frac{1}{2} \epsilon_{qij} (p_i l_j + l_j p_i) \Leftrightarrow [l_i, p_j] \neq 0$$

\Rightarrow full sym. group is $SO(4)/\mathbb{Z}_2 \sim SO(3) \otimes SO(3)$

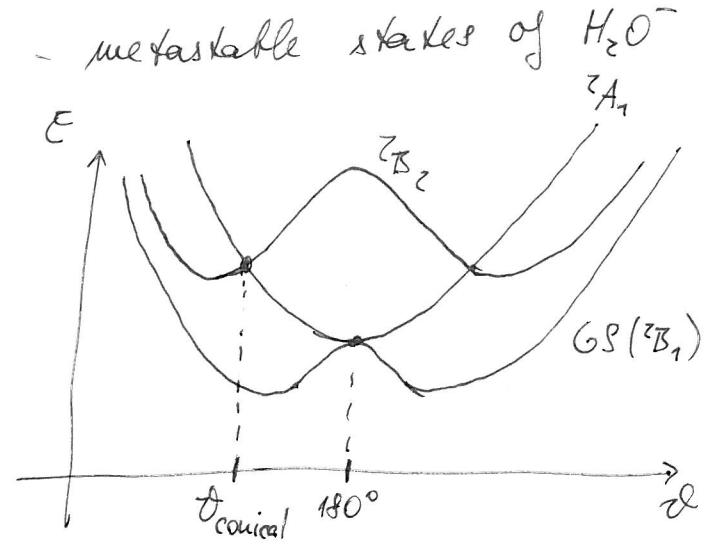
\Rightarrow explains the degeneracy

2, accidental degeneracy - metastable states of H_2O^-



$\Rightarrow C_{2v}$

	E	C_2	σ_v	σ_v'
A_1	1	1	1	1
A_2	1	1	-1	-1
B_1	1	-1	1	-1
B_2	1	-1	-1	1



- $\theta_{conical}$... true accidental degeneracy (G is C_{2v})
- $\theta = 180^\circ$... sym. group is $D_{\infty h}$ & GS is of Π_u sym.

$C_{2v} \hookrightarrow D_{\infty h}$:

	$E \leftrightarrow E$	$C_2 \leftrightarrow \infty C_2$	$\sigma_v \leftrightarrow \sigma_v$	$\sigma_v' \leftrightarrow \infty \sigma_v$	
Π_u	2	0	2	0	$= A_1 \oplus B_2$

NOTE: • here we consider $C_{2v} < D_{\infty h}$ & this is subduction!

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$D_{\infty h}$ point group

not Abelian, ∞ irreducible representations

Character table

	E	$2C_{\infty}^{\varphi}$...	$\infty\sigma_v$	i	$2S_{\infty}^{\varphi}$...	$\infty C_2'$	linear functions, rotations	quadratic
$A_{1g}=\Sigma_g^+$	1	1	...	1	1	1	...	1		x^2+y^2, z^2
$A_{2g}=\Sigma_g^-$	1	1	...	-1	1	1	...	-1	R_z	
$E_{1g}=\Pi_g$	2	$2\cos(\varphi)$...	0	2	$-2\cos(\varphi)$...	0	(R_x, R_y)	(xz, yz)
$E_{2g}=\Delta_g$	2	$2\cos(2\varphi)$...	0	2	$2\cos(2\varphi)$...	0		(x^2-y^2, xy)
$E_{3g}=\Phi_g$	2	$2\cos(3\varphi)$...	0	2	$-2\cos(3\varphi)$...	0		
...		
$A_{1u}=\Sigma_u^+$	1	1	...	1	-1	-1	...	-1	z	
$A_{2u}=\Sigma_u^-$	1	1	...	-1	-1	-1	...	1		
$E_{1u}=\Pi_u$	2	$2\cos(\varphi)$...	0	-2	$2\cos(\varphi)$...	0	(x, y)	
$E_{2u}=\Delta_u$	2	$2\cos(2\varphi)$...	0	-2	$-2\cos(2\varphi)$...	0		
$E_{3u}=\Phi_u$	2	$2\cos(3\varphi)$...	0	-2	$2\cos(3\varphi)$...	0		
...		

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