Time delay observable in classical and quantum geometries

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25 Jun 2012 100 years after Einstein, Prague

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- My answer: Compute qualitative and quantitative QG corrections to experiments and observations.
- Unfortunately, what is easiest to compute in QG is model dependent may not have a direct experimental interpretation.
- Idea: Work backwards! Start with a potential experiment (even if only in principle possible), described operationally. Construct a mathematical model of it and obtain an observable quantity with an unambiguous interpretation.

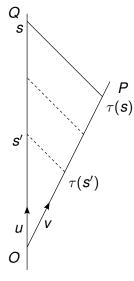
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operational definition

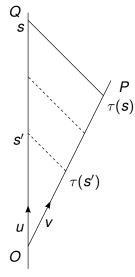


- Consider two inertially moving, localized systems: the lab and the probe. Probe is launched from the lab at event O.
- ► Each carries a proper-time clock. The clocks are synchronized at *O*.
- ► The probe broadcasts signals time stamped with the emission time, τ at P.
- ▶ The lab records the reception time, s at Q, together with the time stamp $\tau(s)$.
- ► The time delay

$$\delta \tau(s) = s - \tau(s)$$

is the observable we seek.

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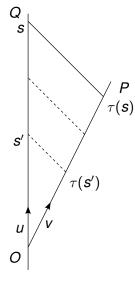


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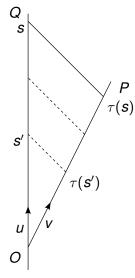


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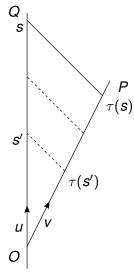


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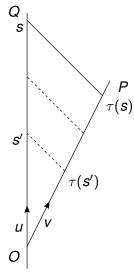


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- ▶ Linearization about Minkowski space: $g_{\mu\nu} \rightarrow \eta_{\mu\nu} + h_{\mu\nu}$.
- ▶ Quantization as linearized field theory: $h_{\mu\nu} \rightarrow \hat{h}_{\mu\nu}$.
- ▶ Explicit expression for $\tau(s)$ at order O(h) is available:

$$\tau(s) = \tau[\eta](s) + \tau_1[h](s) + \cdots$$
$$= se^{-\theta}(1 + r[h] + \cdots)$$
$$r[h] = r^x h_x = H + J$$

- \bullet θ —rapidity, $v_{rel} = \tanh(\theta)$
- ► r^x—integro-differential operator
- ightharpoonup H, ightharpoonup H, ightharpoonup H separately invariant under linearized diffeomorphisms that fix ightharpoonup O and $ightharpoonup e^{lpha}$
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basic idea

- ▶ Vacuum $|0\rangle$ is Gaussian wrt $\hat{\tau}$, with mean $\tau_{\rm cl}$. Remains to compute variance: $\langle (\Delta \hat{\tau})^2 \rangle = \langle \hat{\tau}^2 \rangle \langle \tau \rangle^2 = \tau_{\rm cl} \langle \hat{r}^2 \rangle$, with $\hat{r} = r[\hat{h}] = r^x \hat{h}_x$.
- ▶ Variance needs the Hadamard 2-point function G(x, y).

$$\langle 0|\hat{r}^2|0\rangle = \frac{1}{2}\langle \{\hat{r},\hat{r}\}\rangle = \frac{1}{2}r^xr^y\langle \{\hat{h}_x,\hat{h}_y\}\rangle = \frac{1}{2}r^xr^yG(x,y)$$

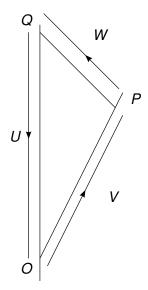
Integrals in r^x are not sufficient to tame the $x-y\to 0$ divergence of $G(x,y)\sim \ell_p^2/(x-y)^2$. Need to use smeared fields \tilde{h} :

$$\tilde{r} = r^{x} \tilde{h}_{x} = r^{x} \langle \langle \hat{h}_{x-z} \rangle \rangle,$$

 $\langle \langle f(z) \rangle \rangle = \int dz f(z) \tilde{g}(z),$

where $\tilde{g}(z)$ is a smearing function, localized at z=0, of spread $\mu \ll s$: $\langle \langle z^n \rangle \rangle \sim \mu^n$.

explicit expressions



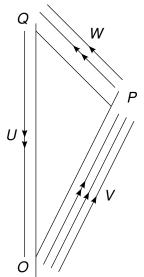
$$r^{x}h_{x}=H+J$$

Explicit expression:

$$H \sim \sum_{X=V,U,W} (\longrightarrow)_X,$$
$$(\longrightarrow)_X \sim \int_{Y}^{(1)} \nabla h.$$

 H is invariant under linearized diffeomorphisms that fix O and e^α.

explicit expressions



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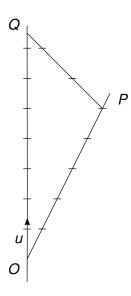
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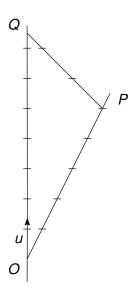
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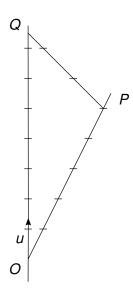
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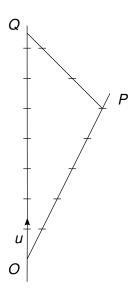
- ▶ In QED, $\langle E(x)^2 \rangle$ diverges, but $\langle \tilde{E}(x)^2 \rangle$ is finite and represents the vacuum noise in a detector of sensitivity profile $\tilde{g}(x)$.
- ▶ Physically speaking, μ , the spread of $\tilde{g}(x)$, is the spatial resolution of the detector.
- We can back-of-envelope estimate μ as the wavelength of the light/radio signals exchanged between lab and probe.
- A more detailed detector model should unambiguously fix $\tilde{g}(x)$ for each leg of $\triangle OPQ$.
- ▶ Provisionally, set $\tilde{g}(x) \sim \delta(u \cdot x)g(x_{\perp}^2)$ everywhere.



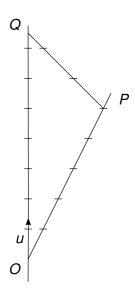
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dimensional analysis

▶ Dimensional analysis: $[\mu] = [\ell_p] = [z] = 1$, $[\nabla] = -1$, $G \sim \ell_p^2/z^2$.

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- Expected rms fluctuation in $\hat{\tau}(s) \sim s\sqrt{\langle \tilde{r}^2 \rangle} \sim s\frac{\ell_p}{\mu} \ \ \text{or} \ \ s\frac{s^{1/2}}{\mu^{1/2}}\frac{\ell_p}{\mu}.$ $\mu \sim 1$ nm (X-rays)

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Thank you for your attention!