

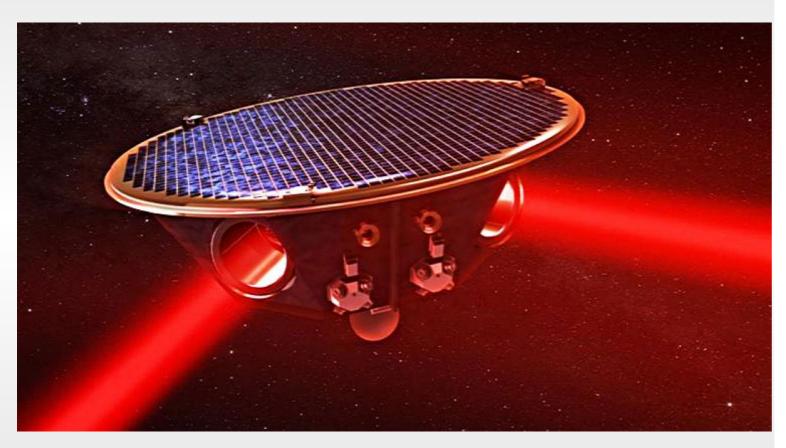
LISA Mission and the Czech involvement

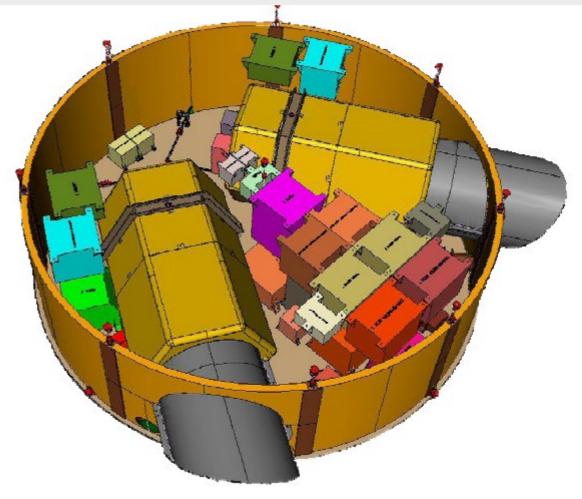
Asen Christov

(on behalf of the teams from FZU, UFA, IT, ASU) 29.9.2021



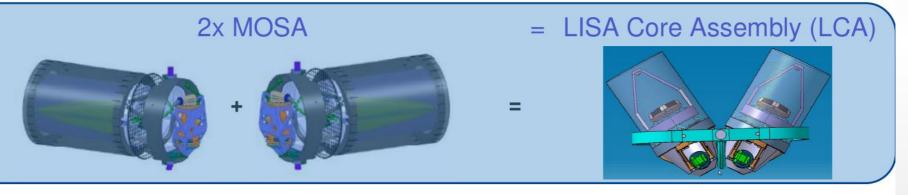
Laser Interferometer Space Antenna





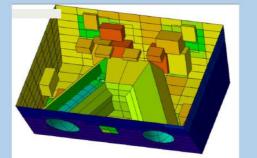




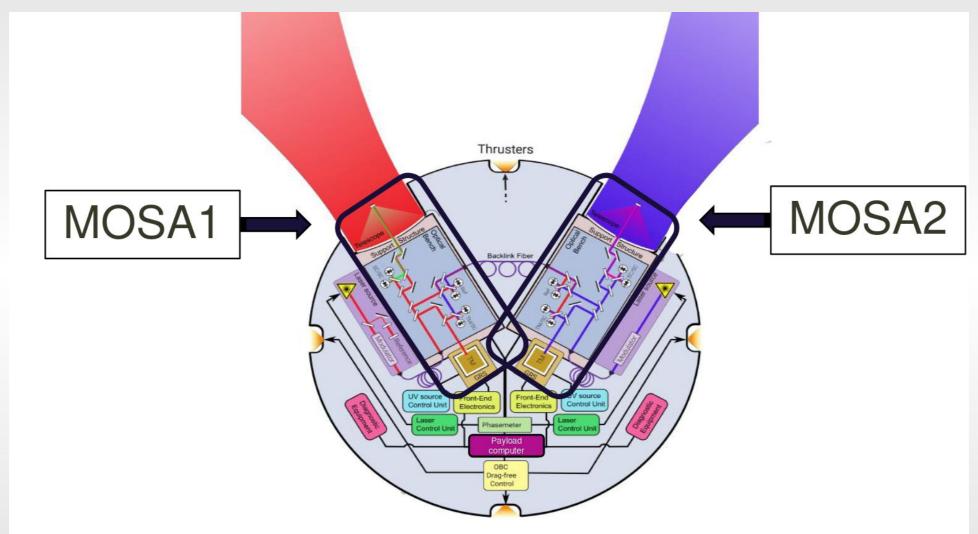


LCA + Electronics boxes = Payload

(Phasemeter, Laser Assembly, GRS FEE,
Computers (on-board+payload), etc.)



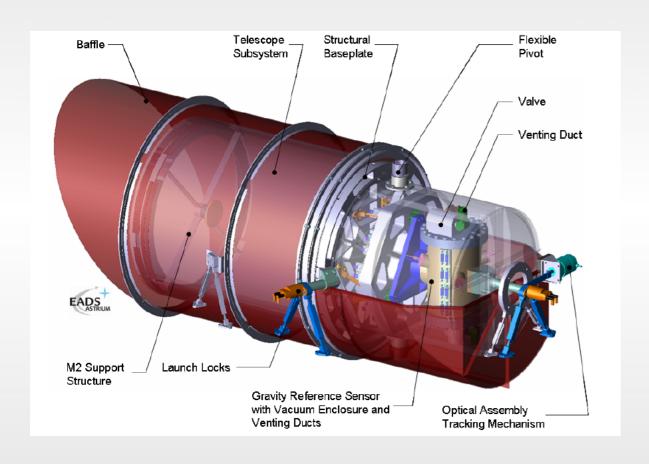


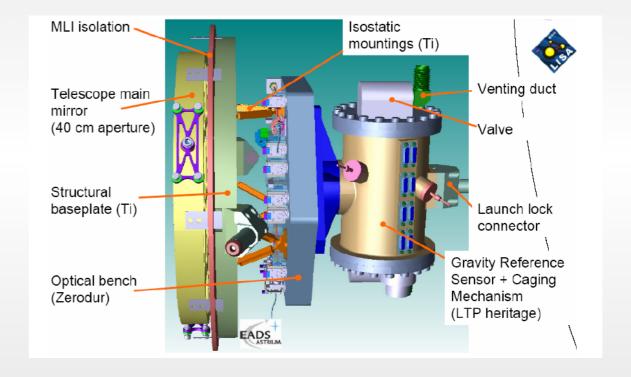


MOSA = Moving Optical Sub-Assembly

- Telescope (T) + Optical Bench (OB) + Gravitational Reference Sensor (GRS) mounted on a mechanical structure
- Additional subsystems (i.e. laser, phasemeter, diagnostics) are required for performance validation

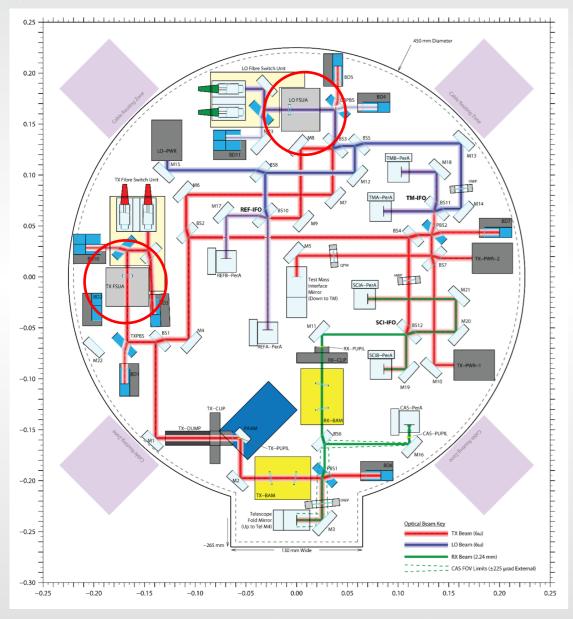






FSUA



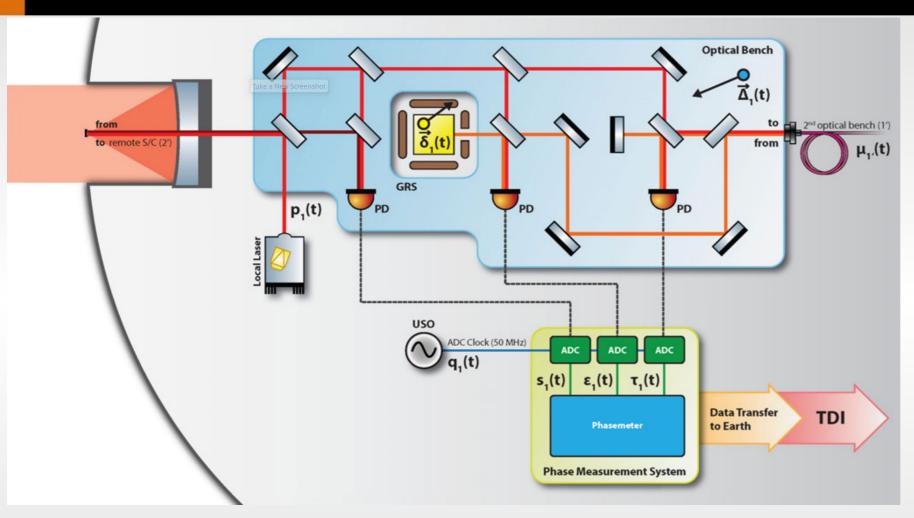


Each optical bench:

- TX FSUA:
 - Laser light 1.2 W,
 - small fraction is used for local interferometry
 - most over the Point-Ahead Angle Mechanism to the remote spacecraft.
- LO FSUA:
 - obtained from the TX laser on the second OB of the spacecraft via the Backlink Fiber.
 - allows to establish a phase reference between the two independent TX lasers on board each spacecraft
- (RX beam): received from the distant spacecraft

Distance measurement





- s1 distant spacecraft signal
- $\varepsilon 1$ test mass signal
- $\tau 1$ reference signal

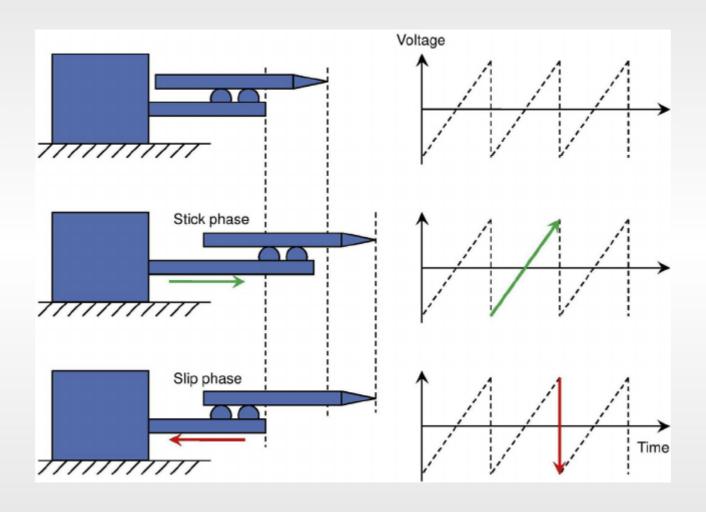
Czech contribution



- Responsible for developing, testing and manufacturing a mechanism for switching between the two laser beams on each spacecraft, the "Fibre Switch Unit Actuator" FSUA.
- The physics Institute, CAS
- The Institute of Atmospheric Physics, CAS
- The Institute of Thermomechanics, CAS
- The Astronomical Institute, CAS
- number of Czech companies
- 400 000 EUR from the contribution of the Ministry of Education, Youth and Sports to the ESA PRODEX programme.
- The total cost of the Czech participation is expected to reach 5.3 million EUR.

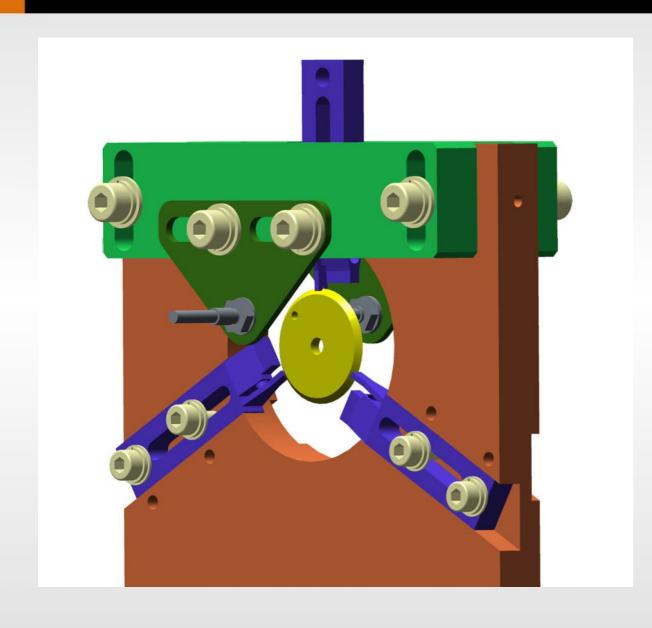
Slip-Stick piezo drive

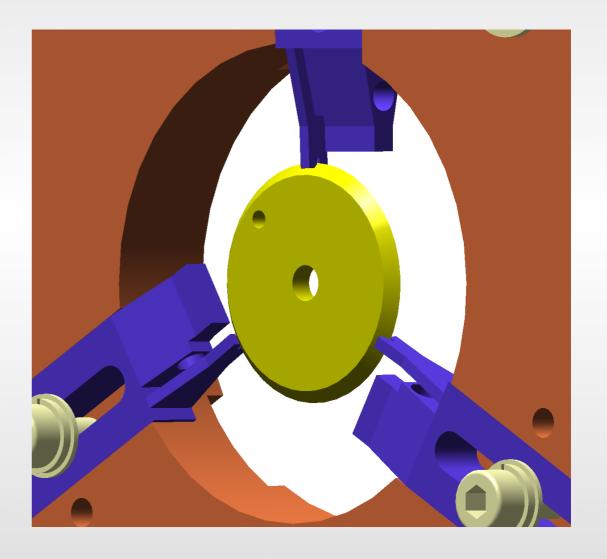




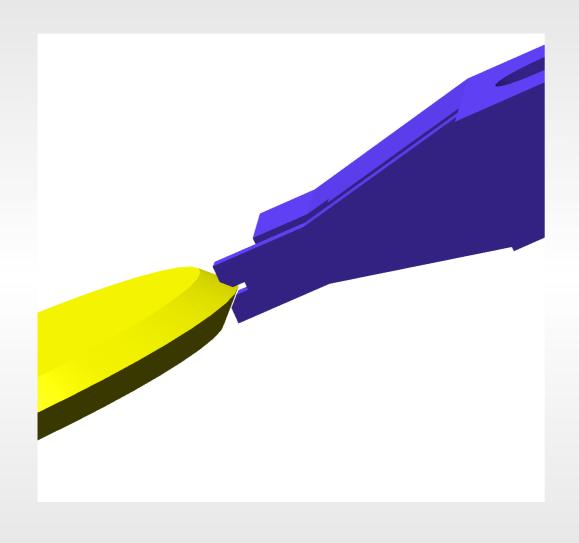
Test Stand

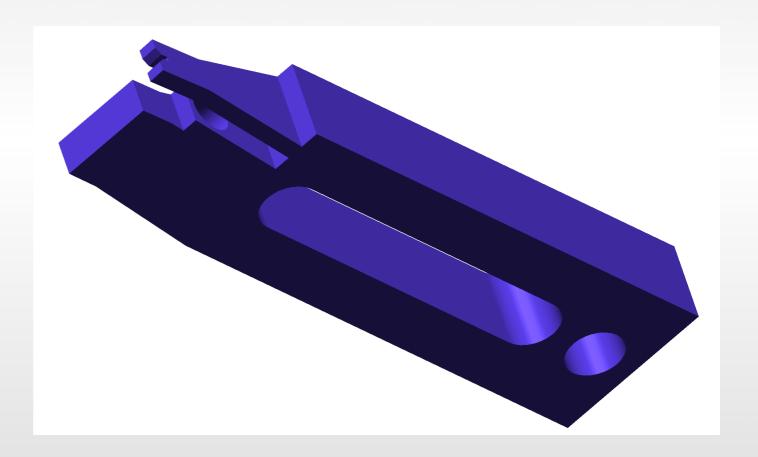






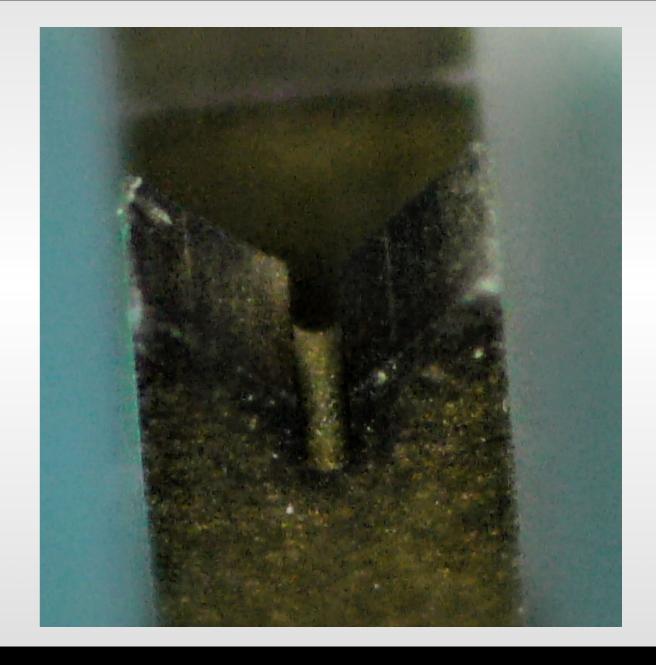




















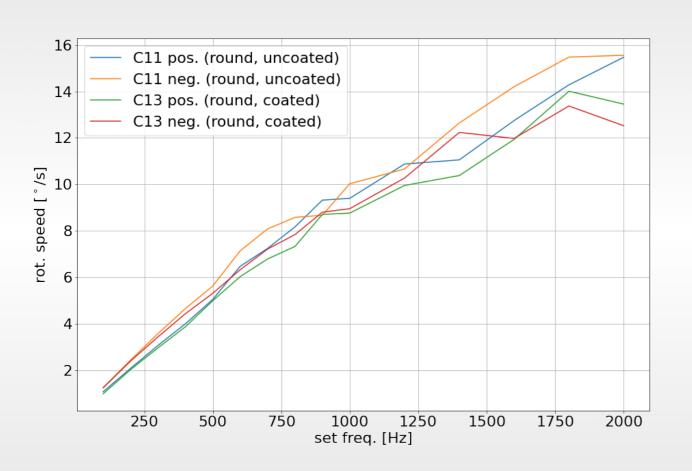






Rotation speed in air



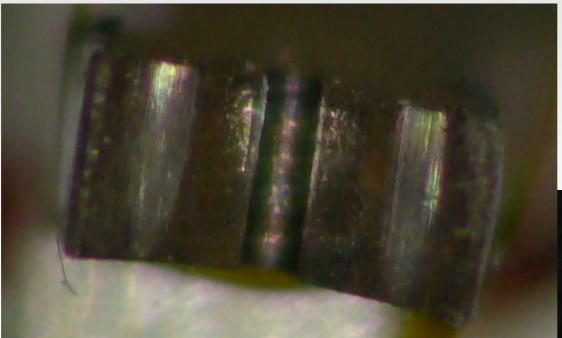


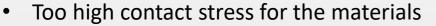
- Consistent results in both directions
- Coatings do not have significant impact

Damage after 6700 rotations

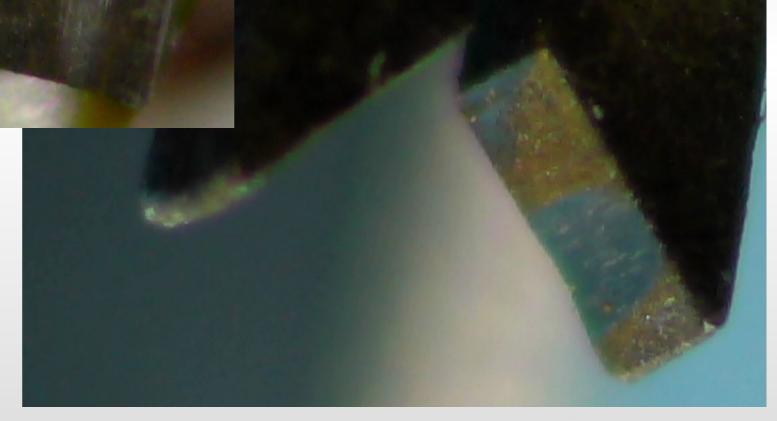








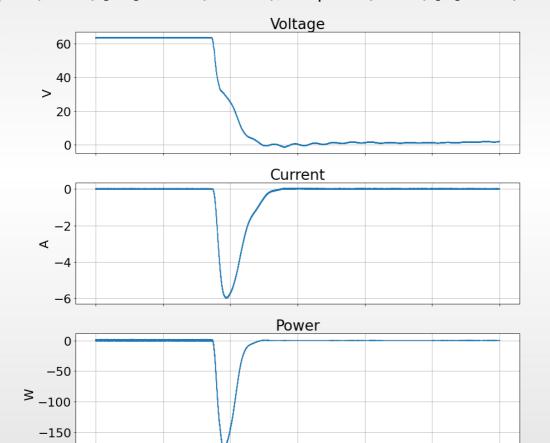
- Too low force holding the rotor
- → We need to change the design concept





Power consumption measurements

Freq set(meas) [Hz] = 300(282.00), Ampl set(meas) [V] = 54(61.57)



0.90

0.95

1.00

1.05

time [s]

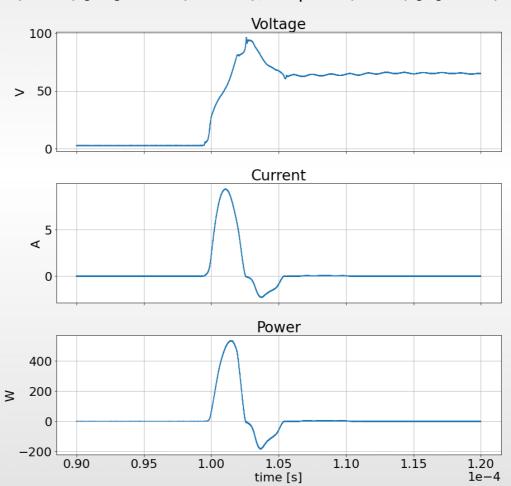
1.10

1.15

1.20

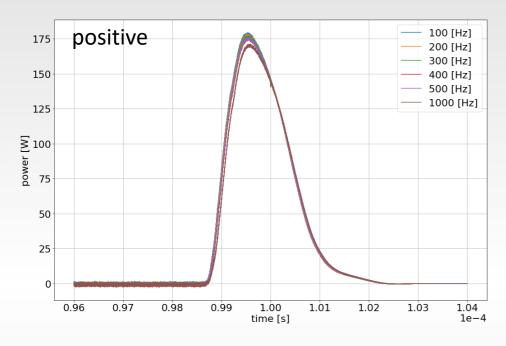
1e-4

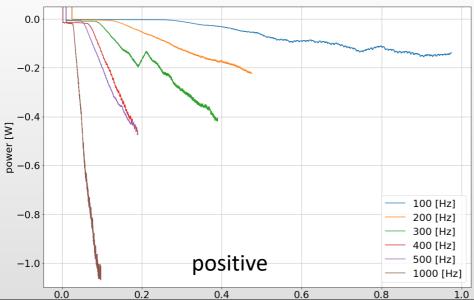
Freq set(meas) [Hz] = 300(282.71), Ampl set(meas) [V] = 54(62.24)

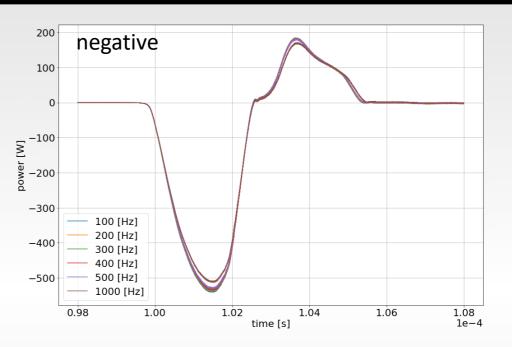


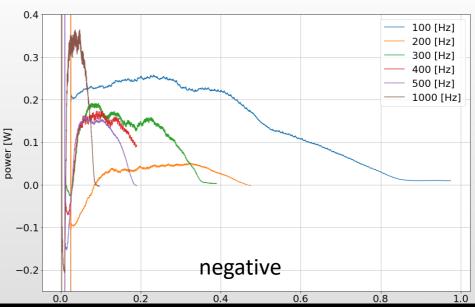
Frequency dependence





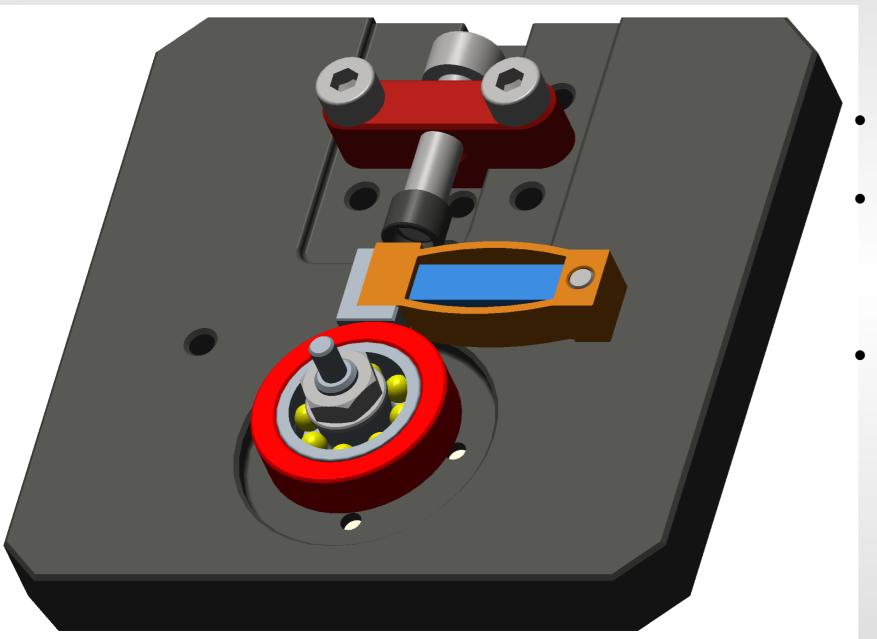






IT test stand



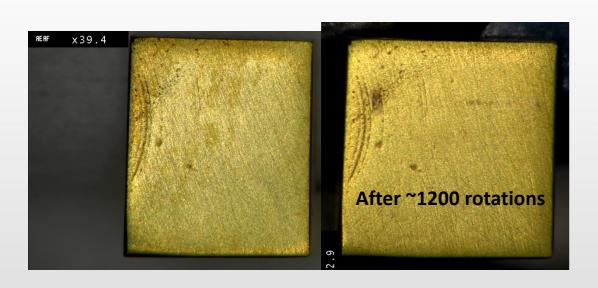


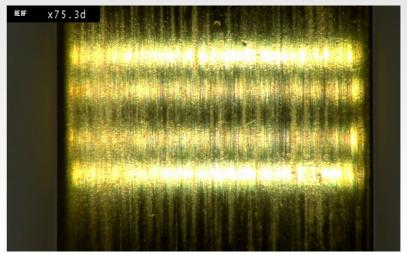
- Different configuration
- Lower contact stress

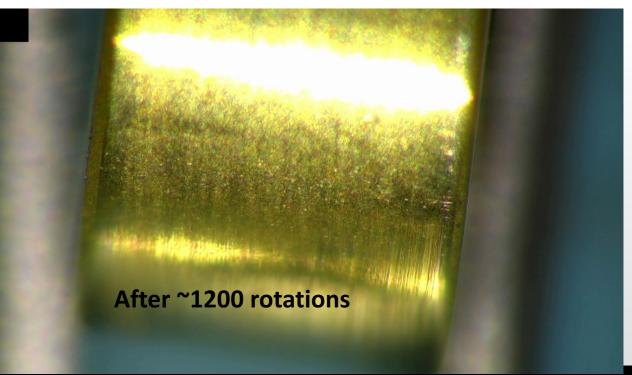
 Testing different combinations of surfaces











Cold welding

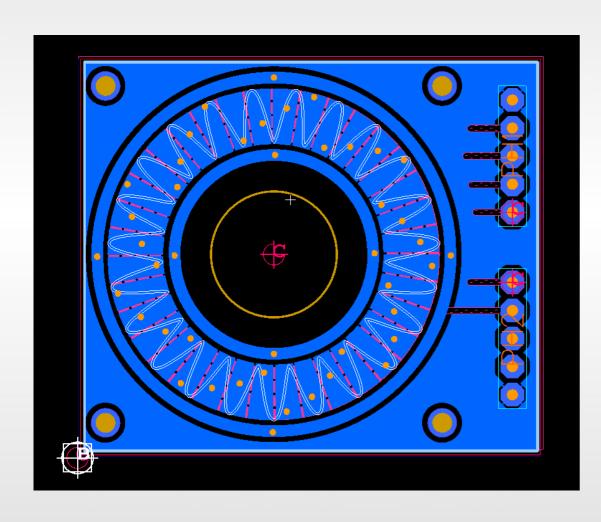


- Parts made of the same metal
- Very flat
- Vacuum
- No movement for a long time

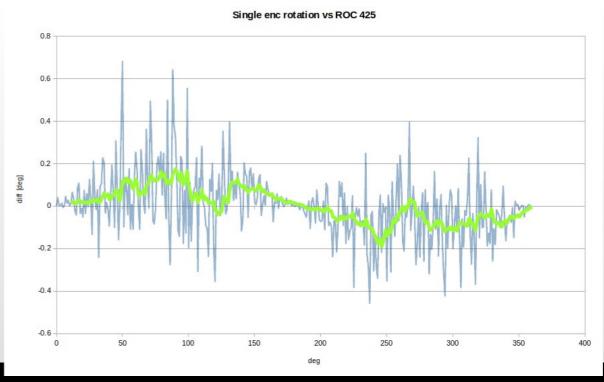
- Prevention: coating with different materials
- Advantage: Tribology layer

FZU Institute of Physics of the Czech Academy of Sciences

Position encoder - Institute of Atmospheric Physics

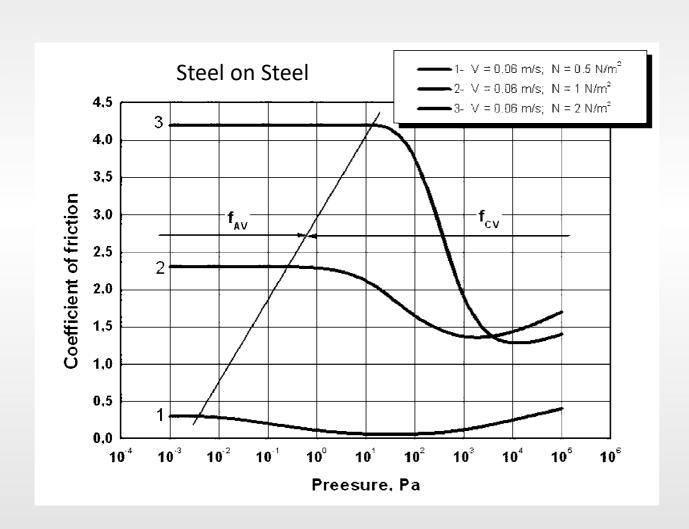


- High precision
- Absolute position
- Strict spatial limitations
- Capacitive sensing



Testing in vacuum





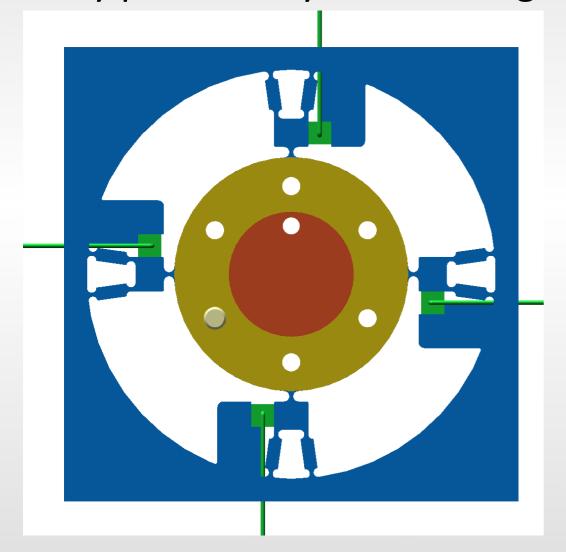
- Moving our test stands to vacuum
- Friction changes
- Heat dissipation changes

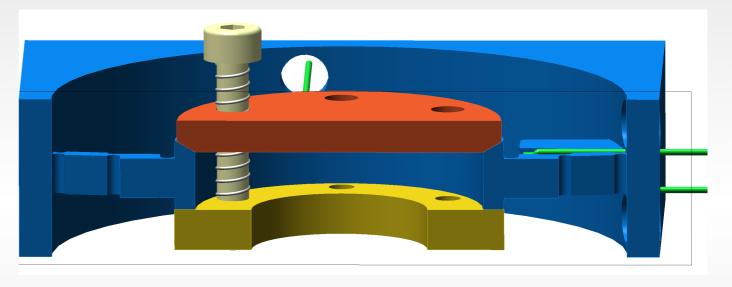
Crucial set of tests





Very preliminary – next design iteration





- + Larger contact surfaces
- Heavier
- +-? Cold welding