

```
In[ ]:= Clear["Global`*"];
```

---

## Problem

Solve numerically the differential equation

$$\frac{\partial u(x, t)}{\partial t} = c \frac{\partial u(x, t)}{\partial x} \quad (1)$$

with the following initial condition

$$u(x, 0) = e^{-x^2} \quad (2)$$

and Dirichlet boundary conditions

$$u(-\infty, t) = 0 \quad (3)$$

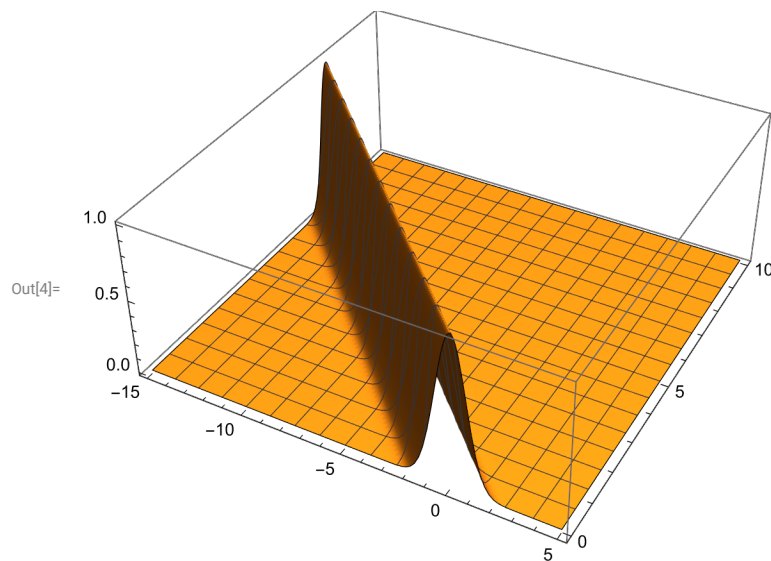
$$u(+\infty, t) = 0$$

---

## Exact solution

```
In[1]:= c = 2;  
u0[x_, t_] = Exp[-(c t + x)^2];  
sol = DSolve[{D[u[x, t], t] == c D[u[x, t], x], u[x, 0] == u0[x, 0]}, u, {x, t}]  
Plot3D[u[x, t] /. sol, {x, -15, 5}, {t, 0, 10}, PlotRange -> All, PlotPoints -> 100]
```

```
Out[3]= {{u -> Function[{x, t}, e^{-4 (t + \frac{x}{2})^2}]}}
```



## Numerical solution using built-in function

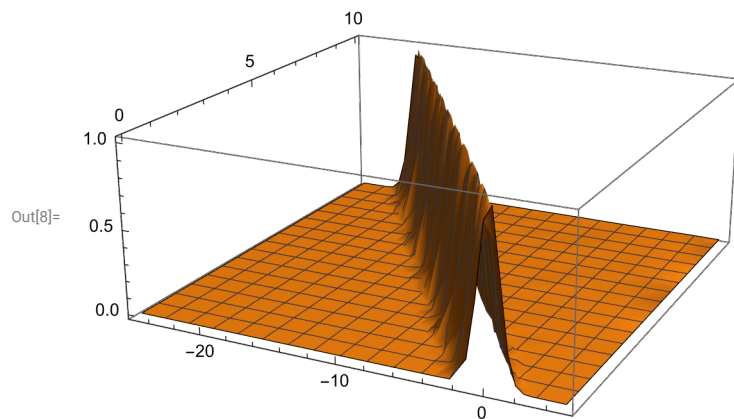
```
In[5]:= {xmin, xmax} = {-25, 5};
        {tmin, tmax} = {0, 10};
        numsol = NDSolve[{D[u[x, t], t] == c D[u[x, t], x], u[x, 0] == u0[x, 0],
            u[xmin, t] == u0[xmin, 0], u[xmax, t] == u0[xmax, 0]}, u, {x, xmin, xmax}, {t, tmin, tmax}]
        Plot3D[Evaluate[u[x, t] /. numsol], {x, xmin, xmax}, {t, tmin, tmax}, PlotRange -> All]
```

```
Out[7]= {{u -> InterpolatingFunction[  

  {+  Domain: {{-25., 5.}, {0., 10.}}  

  Output: scalar  

  Data not in notebook. Store now  ]}}
```



## Numerical solution using basic explicit methods

```
In[89]:= (* grid initialization *)
        {nx, nt} = {301, 271};
        dx = (xmax - xmin) / (nx - 1);
        dt = (tmax - tmin) / (nt - 1);
        Print["λ = ", λ = c N[dt / dx]]
        X = N[Range[xmin, xmax, dx]];
        T = N[Range[tmin, tmax, dt]];

        (* Initialization of the array with zeroes - Dirichlet's boundary conditions *)
        v = ConstantArray[0.0, {nx, nt}];
        error = ConstantArray[0.0, nt];

        (* Initial state *)
        Do[v[[i, 1]] = N[u0[X[[i]], tmin]], {i, 2, nx - 1}];
        Do[v[[i, 2]] = N[u0[X[[i]], tmin + dt]], {i, 2, nx - 1}];
        method = 5;
```

```

Which[
  method == 1,
  Print["Euler explicit method - order 1, unstable"];
  Do[v[[j, n + 1]] = v[[j, n]] +  $\lambda$  / 2 (v[[j + 1, n]] - v[[j - 1, n]]), {n, 1, nt - 1}, {j, 2, nx - 1}],
  method == 2,
  Print["Upwind - order 1, stable  $\lambda \leq 1$ "];
  Do[v[[j, n + 1]] = v[[j, n]] +  $\lambda$  (v[[j + 1, n]] - v[[j, n]]), {n, 1, nt - 1}, {j, 2, nx - 1}],
  method == 3,
  Print["Lax-Friedrichs method - order 1, stable  $\lambda \leq 1$ "];
  Do[v[[j, n + 1]] = 0.5 (v[[j + 1, n]] + v[[j - 1, n]]) +  $\lambda$  / 2 (v[[j + 1, n]] - v[[j - 1, n]]),
    {n, 1, nt - 1}, {j, 2, nx - 1}],
  method == 4,
  Print["Leap-frog method - order 2, stable  $\lambda < 1$ "];
  Do[v[[j, n + 1]] = v[[j, n - 1]] +  $\lambda$  (v[[j + 1, n]] - v[[j - 1, n]]), {n, 2, nt - 1}, {j, 2, nx - 1}],
  method == 5,
  Print["Leap-frog method 4th order in space- order 2, stable  $\lambda < 0.728\dots$ "];
  Do[v[[j, n + 1]] = v[[j, n - 1]] + 4  $\lambda$  (v[[j + 1, n]] - v[[j - 1, n]]) / 3 -  $\lambda$  (v[[j + 2, n]] - v[[j - 2, n]]) / 6,
    {n, 2, nt - 1}, {j, 3, nx - 2}],
  method == 6,
  Print["Lax-Wendroff method - order 2, stable  $\lambda \leq 1$ "];
  Do[v[[j, n + 1]] = v[[j, n]] +  $\lambda$  / 2 (v[[j + 1, n]] - v[[j - 1, n]]) +
     $\lambda^2$  / 2 (v[[j + 1, n]] - 2 v[[j, n]] + v[[j - 1, n]]), {n, 1, nt - 1}, {j, 2, nx - 1}]
];
Do[
  error[[n]] = 0.0;
  Do[
    error[[n]] = Max[error[[n]], Abs[v[[j, n]] - N[u0[X[[j]], T[[n]]]]],
    {j, 2, nx - 1}
  ],
  {n, 1, nt - 1}
]

(* fancy plotting *)
Manipulate[
  n = Round[t / dt] + 1;
  ListLinePlot[{{Table[{X[[j]], u0[X[[j]], T[[n]]}], {j, 1, nx}},
    Table[{X[[j]], v[[j, n]]}, {j, 1, nx}],
  PlotRange -> {-0.5, 1.5}],
  {t, tmin, tmax, dt}

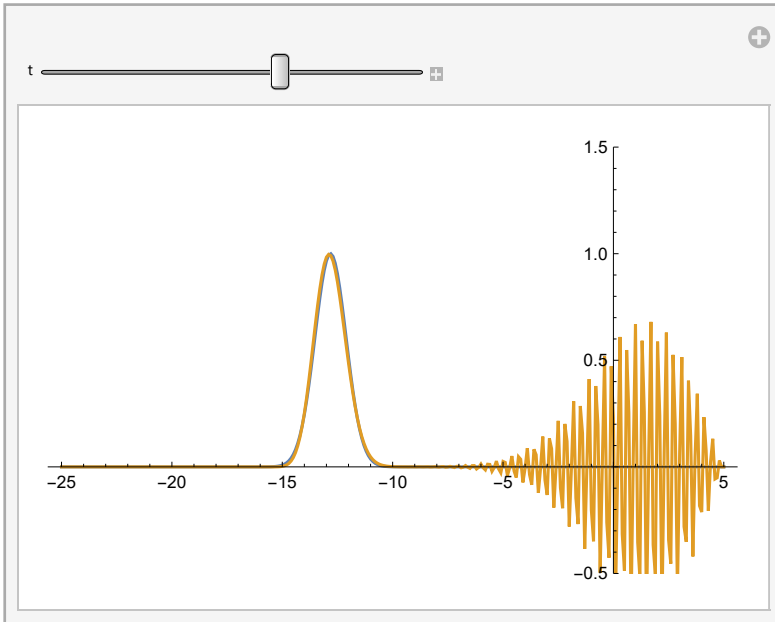
(* show maximal errors *)
ListLogPlot[{{Table[{T[[n]], error[[n]]}, {n, 1, nt}]},
  PlotRange -> All]
Print["Maximal error: ", Max[error]]

 $\lambda = 0.740740740741$ 

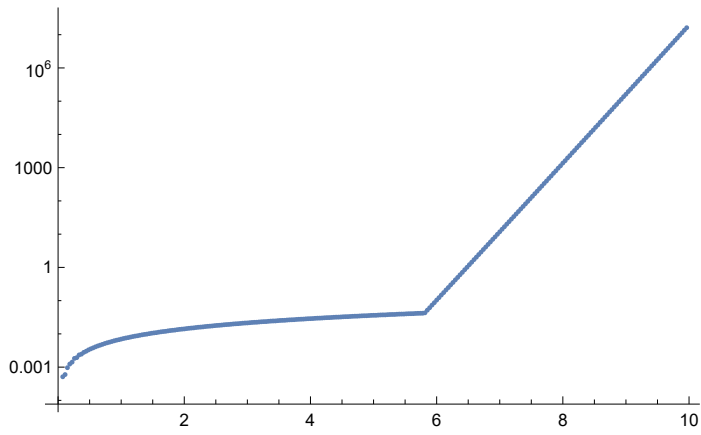
Leap-frog method 4th order in space- order 2, stable  $\lambda < 0.728\dots$ 

```

Out[102]=



Out[103]=



Maximal error:  $1.61960234239 \times 10^7$