

Extensions (prolongations) of infinitesimal transformations

- in the first lecture, we showed how to extend (prolong) a local Lie group of transformations into the space of derivatives of any order
- here we are interested in the extension of infinitesimal transformations, let us consider 1-par. LGT

$$\tilde{x}^i = F^i(x, u, \varepsilon) = x^i + \varepsilon \xi^i(x, u) + O(\varepsilon^2)$$

$$\tilde{u}^M = G^M(x, u, \varepsilon) = u^M + \varepsilon \eta^M(x, u) + O(\varepsilon^2)$$

and find its extension, which we will write as

$$\tilde{u}_i^M = H_i^M(x, u, \partial u, \varepsilon) = u_i^M + \varepsilon \gamma_i^M(x, u, \partial u) + O(\varepsilon^2)$$

⋮

$$\tilde{u}_{i_1 \dots i_k}^M = H_{i_1 \dots i_k}^M(x, u, \partial u, \dots, \partial^k u, \varepsilon) = u_{i_1 \dots i_k}^M + \varepsilon \gamma_{i_1 \dots i_k}^M(x, u, \partial u, \dots, \partial^k u) + O(\varepsilon^2)$$

- we can use the previous result for $H_i^M, \dots, H_{i_1 \dots i_k}^M$ and by keeping terms of the order ε , we get for the first derivatives

$$\begin{pmatrix} \tilde{u}_1^M \\ \vdots \\ \tilde{u}_n^M \end{pmatrix} = \begin{pmatrix} H_1^M \\ \vdots \\ H_n^M \end{pmatrix} = \bar{A}^{-1} \begin{pmatrix} D_1 G^M \\ \vdots \\ D_n G^M \end{pmatrix} = \begin{pmatrix} D_1 F^1 & \dots & D_1 F^n \\ \vdots & \ddots & \vdots \\ D_n F^1 & \dots & D_n F^n \end{pmatrix}^{-1} \begin{pmatrix} D_1 G^M \\ \vdots \\ D_n G^M \end{pmatrix} \quad \begin{matrix} \text{now we keep} \\ \text{only terms} \\ \text{up to order } \varepsilon \end{matrix}$$

$$= \begin{pmatrix} 1 + \varepsilon D_1 \xi^1 & \varepsilon D_1 \xi^2 & \dots & \varepsilon D_1 \xi^n \\ \varepsilon D_2 \xi^1 & 1 + \varepsilon D_2 \xi^2 & & \vdots \\ \vdots & & \ddots & \\ \varepsilon D_n \xi^1 & \dots & & 1 + \varepsilon D_n \xi^n \end{pmatrix}^{-1} \begin{pmatrix} u_1^M + \varepsilon D_1 \eta^M \\ \vdots \\ u_n^M + \varepsilon D_n \eta^M \end{pmatrix} =$$

here we use that for $A = 1 + \varepsilon B$ we have $A^{-1} = 1 - \varepsilon B$ to the order ε

$$\begin{pmatrix} 1 - \varepsilon D_1 \xi^1 & \dots & -\varepsilon D_1 \xi^n \\ \vdots & \ddots & \vdots \\ -\varepsilon D_n \xi^1 & \dots & 1 - \varepsilon D_n \xi^n \end{pmatrix} \begin{pmatrix} u_1^M + \varepsilon D_1 \eta^M \\ \vdots \\ u_n^M + \varepsilon D_n \eta^M \end{pmatrix} =$$

$$= \begin{pmatrix} u_1^M + \varepsilon \left[D_1 \eta^M - \sum_{i=1}^n (D_1 \xi^i) u_i^M \right] + O(\varepsilon^2) \\ \vdots \\ u_n^M + \varepsilon \left[D_n \eta^M - \sum_{i=1}^n (D_n \xi^i) u_i^M \right] + O(\varepsilon^2) \end{pmatrix} = \begin{pmatrix} u_1^M + \varepsilon \eta_1^M + O(\varepsilon^2) \\ \vdots \\ u_n^M + \varepsilon \eta_n^M + O(\varepsilon^2) \end{pmatrix}$$

or

$$\boxed{\eta_i^M = D_i \eta^M - \sum_{k=1}^n (D_i \xi^k) u_k^M} \quad \text{for } i=1, \dots, n$$

- we can continue in a similar way for higher derivatives, only instead of $D_1 G^M$ we would use $D_1 H_i^M$; etc.

Finally, we would get the recursive relations

$$\boxed{\eta_{i_1 \dots i_k}^M = D_{i_k} \eta_{i_1 \dots i_{k-1}}^M - \sum_{j=1}^n (D_{i_k} \xi^j) u_{i_1 \dots i_{k-1} j}^M}$$

for all derivatives up to order k (or higher)

- corresponding extension of the infinitesimal operator X into the space of derivatives up to order k is

$$X^{(k)} = \underbrace{\sum_{i=1}^n \xi^i \frac{\partial}{\partial x^i}}_X + \sum_{m=1}^m \eta^m \frac{\partial}{\partial u^m} + \sum_{i_1^m} \eta_{i_1^m}^m \frac{\partial}{\partial u_{i_1^m}^m} + \dots + \sum_{i_1 \dots i_k}^m \eta_{i_1 \dots i_k}^m \frac{\partial}{\partial u_{i_1 \dots i_k}^m}$$

- in the case of ordinary differential equations with x being independent and y being dependent variables

we will use $\tilde{x} = F(x, y, \varepsilon) = x + \varepsilon \xi(x, y) + O(\varepsilon^2)$

$$\tilde{y} = G(x, y, \varepsilon) = y + \varepsilon \eta(x, y) + O(\varepsilon^2)$$

$$\frac{d\tilde{y}}{d\tilde{x}} \equiv \tilde{y}_1 = H_1(x, y, y_1, \varepsilon) = y_1 + \varepsilon \eta^{(1)}(x, y, y_1) + O(\varepsilon^2)$$

\vdots

$$\frac{d^k \tilde{y}}{d\tilde{x}^k} \equiv \tilde{y}_k = H_k(x, y, y_1, \dots, y_k, \varepsilon) = y_k + \varepsilon \eta^{(k)}(x, y, y_1, \dots, y_k) + O(\varepsilon^2)$$

where now

$$\boxed{\eta^{(1)} = D_x \eta - y_1 D_x \xi, \dots, \eta^{(k)} = D_x \eta^{(k-1)} - y_k D_x \xi}$$

• Examples:

1) translation in the plane (x, y) by a vector (a, b)

$$\begin{aligned} \tilde{x} = x + \varepsilon a &\Rightarrow \xi(x, y) = a \\ \tilde{y} = y + \varepsilon b &\Rightarrow \eta(x, y) = b \end{aligned} \Rightarrow \eta^{(k)} = 0 \text{ for } k \geq 1$$

thus $X^{(k)} = X$ (when we translate a function, its derivatives do not change)

2) scaling of dependent variable

$$\begin{aligned} \tilde{x} = x &\Rightarrow \xi(x, y) = 0 \\ \tilde{y} = e^\varepsilon y &\Rightarrow \eta(x, y) = y \end{aligned} \Rightarrow \eta^{(k)} = y^k \text{ for } k \geq 1$$

thus $X^{(k)} = X + \sum_{i=1}^k \eta_i \frac{\partial}{\partial y_i}$ (derivatives are scaled by the same factor)

3) rotation in the plane (x, y) by an angle ε

$$\begin{aligned} \tilde{x} = x \cos \varepsilon - y \sin \varepsilon &\Rightarrow \xi(x, y) = -y \\ \tilde{y} = x \sin \varepsilon + y \cos \varepsilon &\Rightarrow \eta(x, y) = x \end{aligned} \Rightarrow \begin{aligned} \eta^{(1)} &= 1 + y_1^2 \\ \eta^{(2)} &= 3y_1 y_2 \end{aligned}$$

$$\eta^{(3)} = D_x \eta^{(2)} - y_3 D_x \xi = 3y_2^2 + 4y_1 y_3$$

4) Galilean transformation under which the heat equation

$U_{xx} = U_t$ is invariant:

$$\begin{aligned} \tilde{x} = x + 2t\varepsilon &\Rightarrow \xi^x(x, t, u) = 2t \\ \tilde{t} = t &\Rightarrow \xi^t(x, t, u) = 0 \\ \tilde{u} = u e^{-x\varepsilon - t\varepsilon^2} &\Rightarrow \eta(x, t, u) = -u x \end{aligned} \Rightarrow$$

we get

$$\begin{aligned} \eta_x &= D_x \eta - \overset{0}{(D_x \xi^x)} U_x - \overset{+}{(D_x \xi^t)} U_t = \\ &= -u - x U_x \end{aligned}$$

$$\begin{aligned} \eta_t &= D_t \eta - (D_t \xi^x) U_x = \\ &= -x U_t - 2U_x \end{aligned}$$

and

$$\eta_{xx} = D_x \eta_x - \overset{0}{(D_x \xi^x)} U_{xx} = -2U_x - x U_{xx}$$

$$\eta_{xt} = D_t \eta_x - (D_t \xi^x) U_{xx} = -U_t - x U_{xt} - 2U_{xx} = \eta_{tx}$$

$$\eta_{tt} = D_t \eta_t - (D_t \xi^x) U_{tx} = -x U_{tt} - 4U_{tx}$$

etc.