

Solving ODE using point symmetries

- knowledge of point symmetries of a given ODE can help us to simplify or to solve this equation, in particular:
 - one-param. LGT under which a given ODE of the first order is invariant transforms the ODE into a solvable form \Rightarrow straightforward integration (if the symmetry is non-trivial, details later)
 - if the ODE is of the second or higher order, such a symmetry can be used to reduce the order
 - if there is an r-param. LGT under which the ODE is invariant, then it can be used to reduce the order by r if the LGT is solvable
- two basic methods:
 - canonical (normal) variables - "natural" variables for a certain 1-par. LGT \Rightarrow a simpler form of the ODE
 - method of differential invariants - rewrite the ODE using expressions invariant under the 1-par. LGT
- in both cases we need to solve PDE of the first order of the type $X_r(x,y) = \{x,y\} \frac{\partial r}{\partial x} + \gamma(x,y) \frac{\partial r}{\partial y} = 0$ or $X_s(x,y) = \{x,y\} \frac{\partial s}{\partial x} + \gamma(x,y) \frac{\partial s}{\partial y} = 1$ such equations can be often solved using the method of characteristics (details can be found in L.C.Evans: PDEs, chapter 3) even for more general case

- let us consider the PDE

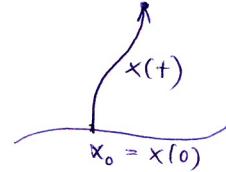
$$\sum_{i=1}^n b^i(x) \frac{\partial v(x)}{\partial x^i} = c(x, v) \quad (*)$$

for an unknown scalar function $v = v(x_1, \dots, x^n)$

- we search a solution along a characteristic

starting at a certain point x_0

where we have the given initial
value $v(x_0) = v_0$



- it can be proved that the solution along
the characteristic given by

$$\frac{dx^i(t)}{dt} = b^i(x(t)) \quad \text{for } i=1, \dots, n, \quad x(0) = x_0$$

satisfies the equation

$$\frac{dv(t)}{dt} = c(x(t), v(t)), \quad v(0) = v(x_0) = v_0.$$

the equations of characteristic can be also written as

$$\frac{dx^1}{b^1(x)} = \frac{dx^2}{b^2(x)} = \dots = \frac{dx^n}{b^n(x)}$$

which is a system of $(n-1)$ equations. The solutions
of this system depend on $(n-1)$ integration constants

- It can be shown, that if we write these constants r_j
as functions of x , they will be $(n-1)$ independent
solutions of $(*)$ with $c(x, v) = 0$, i.e.

$$\sum_{i=1}^n b^i(x) \frac{\partial r_j(x)}{\partial x^i} = 0 \quad \text{for } j=1, \dots, n-1$$

(in this case we have $\frac{dv(t)}{dt} = 0 \Rightarrow v(t) = \text{const} = v_0$
along the characteristic)

- if $c(x, v) \neq 0$, then if $s(x)$ is a solution of $(*)$

then also $s(x) + \sum_{j=1}^{n-1} \alpha^j r_j(x)$ is a solution

- for $c(x, v) = 1$ we can write

$$dt = \frac{ds}{\alpha^i} = \frac{dx^i}{b^i(x)} \quad \text{for a certain } i \text{ and integrate}$$