

STATICKÝ PROSTOROVÝ

Killi-gův vektor ξ kolný k nadploše

\Rightarrow lze zvolit 3+1 rozštěpení přírůbku ξ

$$\vec{T} = \xi \quad t = \text{konst} \text{ kolmé na } \vec{T} \quad \Rightarrow \quad \vec{N} = 0 \quad N = |\xi^a \xi^b g_{ab}|^{\frac{1}{2}}$$

Řádová veličina \propto nezávislá na t

$$\dot{N} = 0 \quad \dot{q} = 0 \quad \dot{V} = 0$$

prostorové bi-distribuce (na Σ)

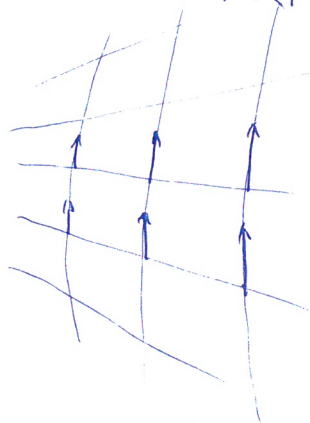
$$\tilde{q} = \frac{1}{N} g^{\frac{1}{2}} \delta$$

$$\tilde{\nu} = \overset{\Sigma}{\underset{\Sigma}{d_a}} \cdot (N g^{ab} g^{\frac{1}{2}} \delta) \cdot \tilde{\alpha}_b + N V g^{\frac{1}{2}} \delta$$

$$\tilde{\mu} = 0$$

$$\dot{\tilde{q}} = 0$$

$$\dot{\tilde{\nu}} = 0$$



Hamiltonian

$$H = \frac{1}{2} (\pi \cdot \tilde{q}^{-1} \cdot \pi + \varphi \cdot \tilde{\nu} \cdot \varphi)$$

$$= \frac{1}{2} \int_{\Sigma} (\pi^2 \tilde{q}^{-1} + d_a \varphi d_b \varphi \tilde{q}^{ab} + V \varphi^2) N g^{\frac{1}{2}}$$

polohové rovnice

$$\dot{\varphi} = \frac{\delta H}{\delta \pi} = \tilde{q}^{-1} \cdot \pi$$

$$\dot{\pi} = -\frac{\delta H}{\delta \varphi} = -\tilde{\nu} \cdot \varphi$$

$$\Downarrow (\tilde{q} \cdot \dot{\varphi})' = -\tilde{\nu} \cdot \varphi$$

$$\Downarrow \ddot{\varphi} + \Omega^2 \cdot \varphi = 0$$

$$\Omega^2 = \tilde{q}^{-1} \cdot \tilde{\nu} \quad \text{frekv. operátor}$$

obecné řešení

$$\varphi(t) = \cos(\Omega t) \cdot \varphi_0 + \Omega^{-1} \sin(\Omega t) \cdot \tilde{q} \cdot \pi_0$$

$$\varphi|_{t=0} = \varphi_0 \quad \pi|_{t=0} = \pi_0$$

definice $\cos(\Omega t)$, $\sin(\Omega t)$ pomocí matic

Frekvenční operátor

$$\begin{aligned} \Omega^2 &= \tilde{q}^{-1} \cdot \tilde{u} \\ &= -N \tilde{g}^{\frac{1}{2}} \tilde{d}_c \cdot [N q^{ab} \tilde{g}^{\frac{1}{2}} \tilde{d}_b] + N V \tilde{g}^{\frac{1}{2}} \delta \\ &= N^2 [-N^2 \overset{\tilde{g}^{ab} \tilde{d}_a \tilde{d}_b}{\Delta} + V] \delta = N^2 [-\Delta + \overset{q^{ab} d_a d_b}{\mathcal{L} d_a} + V] \delta \end{aligned}$$

$\tilde{g}^{ab} \tilde{d}_a \tilde{d}_b \uparrow \quad \tilde{q}_{ab} = N^2 q_{ab}$

Ω^2 pos. def. (pro $N > 0 \quad V > 0$)
 symetrický vůči \tilde{q}
 $\tilde{q} \cdot \Omega^2 = \tilde{u} = \Omega^2 \cdot \tilde{q} \quad \text{t.j.} \quad (\varphi, \Omega^2 \psi)^{\tilde{q}} = \varphi \cdot \tilde{u} \cdot \psi = (\Omega^2 \varphi, \psi)^{\tilde{q}}$

lze defini-ovat fce $F(\Omega^2)$, t.j. i Ω

$$\Omega = [N^2 [-\Delta + \mathcal{L} d_a + V] \delta]^{\frac{1}{2}}$$

vlastní funkce

$$\Omega \cdot v_k = \omega_k v_k \quad \Leftrightarrow \quad \Omega^2 \cdot v_k = \omega_k^2 v_k$$

v_k normaliz. báze $\omega_k \geq 0$

reálné módy

prostor $\mathcal{U}[\Sigma]$ $(\varphi, \psi)^{\tilde{q}} = \varphi \cdot \tilde{q} \cdot \psi = \int_{\Sigma} \varphi(x) \psi(x) \frac{1}{N} \tilde{g}^{\frac{1}{2}}$

Ω symetrická
 $(v_k, v_l)^{\tilde{q}} = \delta_{kl} \quad \sum_k v_k v_k = \tilde{q}^{-1}$

komplexní módy

prostor $\mathcal{U}[\Sigma]^{\mathbb{C}}$ $(\varphi, \psi)^{\tilde{q}} = \varphi^* \cdot \tilde{q} \cdot \psi = \int \varphi^* \psi \frac{1}{N} \tilde{g}^{\frac{1}{2}}$
 Ω hermitovská, reálná

v_k, v_k^* stejné ol. čísla

necht' jsou lin. nez. , t.j. $v_k, v_k^* \leftrightarrow \text{Re } v_k, \text{Im } v_k$
 obsahuje stejnou informaci

$$\begin{aligned} (v_k, v_l)^{\tilde{q}} &= \delta_{kl} & (v_k^*, v_l^*)^{\tilde{q}} &= 0 \\ v_k^* \cdot \tilde{q} \cdot v_l &= \delta_{kl} & v_k \cdot \tilde{q} \cdot v_l &= 0 \end{aligned}$$

$$\tilde{q}^{-1} = \sum_k (v_k^* v_k + v_k v_k^*)$$

Rozštěpení na pos/neg frekvenci řešení

prostory \mathcal{G}^\pm invariantní vůči čas. posun

invariance mód je mód
staví proporcionalita p mód
separace časové a prost. straně.

$$\phi_k^\pm = \text{diff}_{\tilde{q}}(\Delta t) \phi_k^\pm - \text{příslovice}$$

$$\text{diff}_{\tilde{q}}(\Delta t) \phi_k^\pm \sim \phi_k^\pm$$

báze pos/neg řešení

$$\phi_k^+(t, x) = c_k \exp(-i\omega_k t) \mathcal{D}_k(x) \quad \phi_k^+$$

$$\phi_k^-(t, x) = c_k^* \exp(i\omega_k t) \mathcal{D}_k^*(x) \quad \phi_k^-$$

časový posun $t \rightarrow t + \Delta t$

$$\phi_k^\pm \rightarrow \exp(\mp i\omega_k \Delta t) \phi_k^\pm$$

normalizace

$$\mathcal{D}_k \cdot \tilde{q} \cdot \mathcal{D}_l = \delta_{kl} \quad (\text{neup. } \mathcal{D}_k^* \cdot \tilde{q} \cdot \mathcal{D}_l = \delta_{kl} \quad \mathcal{D}_k \cdot \tilde{q} \cdot \mathcal{D}_l = 0)$$

$$\delta_{kl} = \langle \phi_k, \phi_l \rangle = -i(\pi_k^- \cdot \phi_l^+ - \phi_k^- \cdot \pi_l^+) =$$

$$= (\omega_k + \omega_l) c_k^* c_l \mathcal{D}_k^* \cdot \tilde{q} \cdot \mathcal{D}_l = 2\omega_k |c_k|^2 \delta_{kl}$$

$$c_k = \frac{1}{\sqrt{2\omega_k}}$$

↑
pro reálné módy $\mathcal{D}_k^* = \mathcal{D}_k$
pro komplexní módy $\mathcal{D}_k^* \cdot \tilde{q} \cdot \mathcal{D}_l = \delta_{kl}$ } podobně i jiné

$$\phi_k^+(t) = \frac{1}{\sqrt{2\omega_k}} \exp(-i\omega_k t) \mathcal{D}_k$$

reálné módy v \mathcal{G}

$$\phi_k = \phi_k^+ + \phi_k^- = \sqrt{\frac{2}{\omega_k}} \cos(\omega_k t) \mathcal{D}_k = \frac{1}{\omega_k} \cos(\omega_k t) \mathcal{D}_k^R + \frac{1}{\omega_k} \sin(\omega_k t) \mathcal{D}_k^I$$

$$i \cdot \phi_k = i\phi_k^+ - i\phi_k^- = \sqrt{\frac{2}{\omega_k}} \sin(\omega_k t) \mathcal{D}_k = \frac{1}{\omega_k} \sin(\omega_k t) \mathcal{D}_k^R - \frac{1}{\omega_k} \cos(\omega_k t) \mathcal{D}_k^I$$

↑
komplex $\mathcal{D}_k \rightarrow \mathcal{D}_k = \frac{1}{\sqrt{2}} (\mathcal{D}_k^R + i\mathcal{D}_k^I)$

$$(\mathcal{D}_k, \mathcal{D}_l)_{\tilde{q}} = 0 \quad (\mathcal{D}_k, \mathcal{D}_l)_{\tilde{q}} = \delta_{kl} \Leftrightarrow (\mathcal{D}_k^R, \mathcal{D}_l^R)_{\tilde{q}} = \delta_{kl} \quad (\mathcal{D}_k^R, \mathcal{D}_l^I)_{\tilde{q}} = 0$$

obecné řešení

$$\varphi(t) = \cos(\Omega t) \cdot \varphi_0 + \Omega^{-1} \cdot \sin(\Omega t) \cdot \tilde{q} \cdot \tilde{\pi}_0$$

$$= \sum_k (\varphi_{0k} \cos(\omega_k t) \mathcal{D}_k + \pi_{0k} \omega_k^{-1} \sin(\omega_k t) \mathcal{D}_k)$$

$$\text{zde } \varphi_0 = \sum_k \varphi_{0k} \mathcal{D}_k \quad \tilde{q} \cdot \tilde{\pi}_0 = \sum_k \pi_{0k} \mathcal{D}_k$$

↑
 φ_{0k}

Charakteristika (homog. po. det. (reálne δ_k))

$$\varphi_k^\pm(t) = \frac{1}{\sqrt{2\omega_k}} \exp(\mp i\omega_k t) \delta_k$$

$$\hat{q}^{-1} \cdot \ddot{\pi}_k^\pm(t) = \dot{\varphi}_k^\pm(t) = \mp i\omega_k \varphi_k^\pm(t)$$

$$\downarrow$$

$$\varphi \in \mathcal{S}^\pm \Leftrightarrow \dot{\varphi}(t) \equiv \hat{q}^{-1} \cdot \ddot{\pi}(t) = \mp i\Omega \cdot \varphi(t)$$

všechny, obecné res. má tvar

$$\varphi = \sum_k \varphi_{0k} \cos(\omega_k t) \delta_k + \pi_{0k} \omega_k^{-1} \sin(\omega_k t) \delta_k$$

$$= \underbrace{\sum_k \frac{1}{2} (\varphi_{0k} - \frac{i}{\omega_k} \pi_{0k}) \exp(i\omega_k t) \delta_k}_{\varphi^-} + \underbrace{\sum_k \frac{1}{2} (\varphi_{0k} + \frac{i}{\omega_k} \pi_{0k}) \exp(-i\omega_k t) \delta_k}_{\varphi^+}$$

$$= \frac{1}{2} \exp(i\Omega t) \cdot (\varphi_0 - i\Omega \cdot \hat{q}^{-1} \cdot \pi_0) + \frac{1}{2} \exp(-i\Omega t) \cdot (\varphi_0 + i\Omega \cdot \hat{q}^{-1} \cdot \pi_0)$$

$$\downarrow$$

$$[\frac{d}{dt} - i\Omega] \varphi^- = 0$$

$$\downarrow$$

$$[\frac{d}{dt} + i\Omega] \varphi^+ = 0$$

Комплексная структура в $3+1$ пространстве

$$\phi \in \mathcal{F}^\pm \Leftrightarrow \pi = \mp i \hat{q} \cdot \Omega \cdot \varphi$$

$$\phi \leftrightarrow \begin{pmatrix} \varphi \\ \pi \end{pmatrix}$$

$$\phi^\pm \leftrightarrow \begin{pmatrix} \varphi^\pm \\ \pi^\pm \end{pmatrix} = \begin{pmatrix} \varphi^\pm \\ \mp i \hat{q} \cdot \Omega \cdot \varphi^\pm \end{pmatrix}$$

$$\phi = \phi^+ + \phi^- \leftrightarrow \begin{pmatrix} \varphi \\ \pi \end{pmatrix} = \begin{pmatrix} \varphi^+ + \varphi^- \\ -i \hat{q} \cdot \Omega \cdot (\varphi^+ - \varphi^-) \end{pmatrix}$$

$$J \cdot \phi^\pm = \pm i \phi^\pm \leftrightarrow \begin{pmatrix} \pm i \varphi^\pm \\ \hat{q} \cdot \Omega \cdot \varphi^\pm \end{pmatrix}$$

$$J \cdot \phi = i(\phi^+ - \phi^-) \leftrightarrow \begin{pmatrix} i(\varphi^+ - \varphi^-) \\ \hat{q} \cdot \Omega \cdot (\varphi^+ + \varphi^-) \end{pmatrix} = \begin{pmatrix} -\Omega^{-1} \cdot \hat{q}^{-1} \cdot \pi \\ \hat{q} \cdot \Omega \cdot \varphi \end{pmatrix} = \begin{pmatrix} 0 & -\Omega^{-1} \hat{q}^{-1} \\ \hat{q} \cdot \Omega & 0 \end{pmatrix} \begin{pmatrix} \varphi \\ \pi \end{pmatrix}$$

$$J \leftrightarrow \begin{pmatrix} 0 & -\Omega^{-1} \hat{q}^{-1} \\ \hat{q} \cdot \Omega & 0 \end{pmatrix}$$

$$P^\pm \Leftrightarrow \frac{1}{2} \begin{pmatrix} \delta & \pm i \Omega^{-1} \hat{q}^{-1} \\ \mp i \hat{q} \cdot \Omega & \delta \end{pmatrix}$$

Diagonalizace Hamiltoniánů

$$\varphi^\pm \Leftrightarrow \phi_k^\pm = \frac{1}{\sqrt{2\omega_k}} \exp(\mp i\omega_k t) \mathcal{D}_k$$

1) toto rozstřepení zaručí, že

$$\hat{H} = :H(\hat{\Phi}): = \sum_k \omega_k \hat{H}_k$$

1) Hamilton. je diag. v bázi \Rightarrow módy ϕ_k

2) požadavek diagonalizace jednod. určuje φ^\pm

Diagonalizace

připomínka:

$$H(\phi) = \frac{1}{2} (\pi \cdot \tilde{q}^{-1} \cdot \pi + \varphi \cdot \tilde{\omega} \cdot \varphi) = \frac{1}{2} (\pi \cdot \tilde{q}^{-1} \cdot \pi + \varphi \cdot \Omega \cdot \tilde{q} \cdot \Omega \cdot \varphi) \left| \begin{array}{l} \phi_k^+ = \frac{1}{\sqrt{2\omega_k}} \exp(\mp i\omega_k t) \mathcal{D}_k \\ \pi_k^\pm = \mp i\omega_k \tilde{q} \cdot \phi_k^\pm \\ \pi^\pm = \mp i \tilde{q} \cdot \Omega \cdot \varphi^\pm \end{array} \right.$$

$$\mathcal{H}(\phi^-, \phi^+) = H(\phi^- + \phi^+) =$$

$$= \frac{1}{2} (\pi^- \cdot \tilde{q}^{-1} \cdot \pi^- + \varphi^- \cdot \Omega \cdot \tilde{q} \cdot \Omega \cdot \varphi^-) + \frac{1}{2} (\pi^+ \cdot \tilde{q}^{-1} \cdot \pi^+ + \varphi^+ \cdot \Omega \cdot \tilde{q} \cdot \Omega \cdot \varphi^+) + \frac{1}{2} (\pi^- \cdot \tilde{q}^{-1} \cdot \pi^+ + \varphi^- \cdot \Omega \cdot \tilde{q} \cdot \Omega \cdot \varphi^+) + \frac{1}{2} (\pi^+ \cdot \tilde{q}^{-1} \cdot \pi^- + \varphi^+ \cdot \Omega \cdot \tilde{q} \cdot \Omega \cdot \varphi^-)$$

$\begin{array}{l} \uparrow \quad \uparrow \\ -i \tilde{q} \cdot \Omega \cdot \varphi^+ \\ i \tilde{q} \cdot \Omega \cdot \varphi^- \end{array}$

$$= 2 \varphi \cdot \Omega \cdot \tilde{q} \cdot \Omega \cdot \varphi$$

$$\mathcal{H}(\phi_k^-, \phi_k^+) = \frac{1}{i\omega_k \omega_k} \exp(i(\omega_k - \omega_k)t) \mathcal{D}_k^+ \cdot \Omega \cdot \tilde{q} \cdot \Omega \cdot \mathcal{D}_k^- = \omega_k \delta_{kk}$$

$$\hat{H} = :H(\hat{\Phi}): = : \mathcal{H} \left(\sum_k \hat{a}_k^+ \phi_k^-, \sum_k \hat{a}_k \phi_k^+ \right) :$$

$$= \sum_{k,l} \hat{a}_k^+ \hat{a}_l \mathcal{H}(\phi_k^-, \phi_l^+) = \sum_k \omega_k \hat{a}_k^+ \hat{a}_k$$

Jednoznačnost částečné interpretace diagonalizující \hat{H}

podmínka, že \hat{H} je diagonální v částečných stavech
jednoznačně určuje částečnou interp., tj. volbu J

- nejde utnout o statický případ

- stačí uvažovat Hamiltonian na nadploše Σ

předpoklad diagonality:

$$\begin{aligned}\hat{H} &= \sum_k \omega_k \hat{n}_k = \sum_k \hat{a}_k^\dagger \omega_k \hat{a}_k = \sum_k \langle \hat{\Phi}, \phi_k \rangle \omega_k \langle \phi_k, \hat{\Phi} \rangle = \\ &= \langle \hat{\Phi}, \mathcal{D} \cdot \hat{\Phi} \rangle = -i \hat{\Phi}^\dagger \cdot \partial \mathcal{F} \cdot \mathcal{D} \cdot \hat{\Phi} = -\frac{1}{2} : \hat{\Phi} \cdot \partial \mathcal{F} \cdot \underbrace{J \cdot \mathcal{D}} \cdot \hat{\Phi} : \end{aligned}$$

operátor \mathcal{D} (různý od $\mathcal{D} = (\hat{q}^{-1} \cdot \hat{p})^2$)

$$\begin{array}{lll} \mathcal{D} \cdot \phi_k = \omega_k \phi_k & [\mathcal{D}, J] = 0 & \mathcal{D} \cdot \partial \mathcal{F} = \partial \mathcal{F} \cdot \mathcal{D} \\ \text{eigenvektory} & J\text{-linearita} & J\text{-hermiticit} \end{array}$$

předpoklad lokalizace na Σ

$$H(\phi) = \frac{1}{2} \phi \cdot \mathcal{H} \cdot \phi \quad \mathcal{H} = \mathcal{H}[\Sigma] \quad H = H[\Sigma]$$

$$\begin{aligned}\hat{H} &= : H(\hat{\Phi}) : = \text{kvantový Hamilt. daný norm. vypoř. klasického} \\ &= \frac{1}{2} : \hat{\Phi} \cdot \mathcal{H} \cdot \hat{\Phi} : = -\frac{1}{2} : \hat{\Phi} \cdot \partial \mathcal{F} \cdot \underbrace{G_0 \cdot \mathcal{H}} \cdot \hat{\Phi} : \end{aligned}$$

porovnáním dostáváme

$$G_0 \cdot \mathcal{H} = J \cdot \mathcal{D} = \mathcal{D} \cdot J$$

plánem dekompozice operátoru $G_0 \cdot \mathcal{H}$ definuje J a \mathcal{D}

$$\mathcal{D} = |G_0 \cdot \mathcal{H}| \quad J = \text{sign}(G_0 \cdot \mathcal{H}) \quad \text{tj.}$$

$$\mathcal{D}^2 = -G_0 \cdot \mathcal{H} \cdot G_0 \cdot \mathcal{H} \quad J = \mathcal{D}^{-1} \cdot G_0 \cdot \mathcal{H}$$

zde se využije, že $(G_0 \cdot \mathcal{H})^\dagger = -G_0 \cdot \mathcal{H}$ pro transpozici T
danou ps. def. bi-lineární formou \mathcal{H}

plánem dekompozice

mějme reálný Hilb. pr. se sk. souč. daný bi-lin. formou B

B definuje transpozici T : $A^T = B^{-1} \cdot A \cdot B$

podobně pro operátor A platí $[A, A^T] = 0$, pak existuje jednoznačná
plánem dekompozice na abs. hodnotu $|A|$ a signum $\text{sign} A$

$$A = (\text{sign} A) \cdot |A| = |A| \cdot (\text{sign} A)$$

$|A|$ symetr. ps. def. $|A| = |A|^T$, $\text{sign} A$ ortogonální $(\text{sign} A) \cdot (\text{sign} A)^T = \mathbb{I}$
kde

$$|A|^2 = A \cdot A^T \quad \text{sign} A = |A|^{-1} \cdot A = A \cdot |A|^{-1}$$

Termální stav

smíšený stav o teplotě $T = \frac{1}{\beta}$ při fixované střední energii

$$\hat{D}_\beta = \frac{1}{Z} \exp(-\beta \hat{H})$$

$$Z = \text{Tr} \exp(-\beta \hat{H})$$

$$\text{Tr} \hat{D}_\beta = 1$$

Hamiltonián - (normálně uspořádaný)

$$\hat{H} = \sum_k \omega_k \hat{n}_k$$

střední hodnota ve stavu \hat{D}_β

$$\langle \hat{A} \rangle_\beta = \text{Tr} (\hat{D}_\beta \hat{A})$$

vakuum

$$\hat{D}_0 = |vac\rangle \langle vac|$$

Platí:

$$Z = \prod_k \frac{1}{1 - \exp(-\beta \omega_k)} = \det^{-1} (1 - \exp(-\beta \Omega))$$

$$\langle \hat{a}_k^\dagger \hat{a}_k \rangle_\beta = \frac{\exp(-\beta \omega_k)}{1 - \exp(-\beta \omega_k)} = \langle \hat{n}_k \rangle$$

$$\langle \hat{a}_k \hat{a}_k^\dagger \rangle_\beta = \frac{1}{1 - \exp(-\beta \omega_k)}$$

$$\langle \hat{a}_k \hat{a}_l \rangle_\beta = \langle \hat{a}_k^\dagger \hat{a}_l^\dagger \rangle_\beta = \langle \hat{a}_k^\dagger \hat{a}_l \rangle_\beta = \langle \hat{a}_k \hat{a}_l^\dagger \rangle_\beta = 0$$

odvození:

$$\begin{aligned}
 Z &= \text{Tr} \exp(-\beta \sum_{\mathbf{z}} \omega_{\mathbf{z}} \hat{n}_{\mathbf{z}}) && \Leftrightarrow \text{Tr} \equiv \sum_{\{m_{\mathbf{z}}\}} \langle \{m_{\mathbf{z}}\} | \dots | \{m_{\mathbf{z}}\} \rangle \\
 &= \sum_{\mathbf{m}} \exp(-\beta \sum_{\mathbf{z}} \omega_{\mathbf{z}} m_{\mathbf{z}}) \\
 &= \prod_{\mathbf{z}} \sum_{m_{\mathbf{z}}=0}^{\infty} \exp(-\beta \omega_{\mathbf{z}} m_{\mathbf{z}}) \\
 &= \prod_{\mathbf{z}} \frac{1}{1 - \exp(-\beta \omega_{\mathbf{z}})} \\
 &= \det^{-1} (1 - \exp(-\beta \Omega))
 \end{aligned}$$

$$\begin{aligned}
 \langle \hat{a}_{\mathbf{z}}^+ \hat{a}_{\mathbf{z}} \rangle_{\beta} &= \text{Tr} (\hat{D}_{\beta} \hat{n}_{\mathbf{z}}) = \frac{1}{Z} \text{Tr} (\hat{n}_{\mathbf{z}} \exp(-\beta \hat{H})) \\
 &= \frac{1}{Z} \sum_{\mathbf{m}} m_{\mathbf{z}} \exp(-\beta \sum_{\mathbf{l}} m_{\mathbf{l}} \omega_{\mathbf{l}}) = \\
 &= (1 - \exp(-\beta \omega_{\mathbf{z}})) \left(\sum_{m_{\mathbf{z}}} m_{\mathbf{z}} \exp(-\beta m_{\mathbf{z}} \omega_{\mathbf{z}}) \right) \cdot \\
 &\quad \cdot \prod_{\mathbf{l} \neq \mathbf{z}} (1 - \exp(-\beta \omega_{\mathbf{l}})) \underbrace{\left(\sum_{m_{\mathbf{l}}} \exp(-\beta m_{\mathbf{l}} \omega_{\mathbf{l}}) \right)}_1 \\
 &\stackrel{=}{=} - (1 - \exp(-\beta \omega_{\mathbf{z}})) \frac{1}{\omega_{\mathbf{z}}} \frac{\partial}{\partial \beta} \sum_{m_{\mathbf{z}}} \exp(-\beta m_{\mathbf{z}} \omega_{\mathbf{z}}) \\
 &= - (1 - \exp(-\beta \omega_{\mathbf{z}})) \frac{1}{\omega_{\mathbf{z}}} \frac{\partial}{\partial \beta} \frac{1}{1 - \exp(-\beta \omega_{\mathbf{z}})} \\
 &= \frac{1 - \exp(-\beta \omega_{\mathbf{z}})}{(1 - \exp(-\beta \omega_{\mathbf{z}}))^2} \frac{\omega_{\mathbf{z}}}{\omega_{\mathbf{z}}} \exp(-\beta \omega_{\mathbf{z}}) \\
 &= \frac{\exp(-\beta \omega_{\mathbf{z}})}{1 - \exp(-\beta \omega_{\mathbf{z}})}
 \end{aligned}$$

$$\langle \hat{a}_{\mathbf{z}} \hat{a}_{\mathbf{z}}^+ \rangle_{\beta} = \langle \hat{a}_{\mathbf{z}}^+ \hat{a}_{\mathbf{z}} + \hat{1} \rangle_{\beta} = \frac{\exp(-\beta \omega_{\mathbf{z}})}{1 - \exp(-\beta \omega_{\mathbf{z}})} + 1 = \frac{1}{1 - \exp(-\beta \omega_{\mathbf{z}})}$$