

Rindlerowy sowaadnice

inerc. sowaad. t, z

muloee sowaad. u, v

$$\begin{aligned} u &= t - z & t &= \frac{u+v}{2} \\ v &= t + z & z &= \frac{v-u}{2} \end{aligned}$$

muloee Rindlerowy sowaad. U, V

$$\begin{aligned} u &= s_u \exp(-U) & U &= -\log |u| & s_u &= \text{sign } u \\ v &= s_v \exp(V) & V &= \log |v| & s_v &= \text{sign } v \end{aligned}$$

Rindlerowy sowaad. τ, b

$$U = \tau - \ln b \quad b > 0$$

$$V = \tau + \ln b \quad \tau \in \mathbb{R}$$

$$t^2 - z^2 = uv = s_u s_v \exp(V - U) = s_u s_v b^2 = \begin{matrix} \text{F.P.} \\ \pm \\ \text{L.R.} \end{matrix} b^2$$

R.L. oblasti

$$t = \frac{v+u}{2} = \begin{matrix} \text{R} \\ \pm \\ \text{L} \end{matrix} \frac{1}{2} (e^V - e^{-U}) = \pm b \sinh \tau$$

$$\pm \ln \tau = \frac{t}{z}$$

$$z = \frac{v-u}{2} = \pm \frac{1}{2} (e^V + e^{-U}) = \pm b \cosh \tau$$

$$b^2 = z^2 - t^2$$

F.P. oblast:

$$t = \frac{v+u}{2} = \begin{matrix} \text{F} \\ \pm \\ \text{P} \end{matrix} \frac{1}{2} (e^V + e^{-U}) = \pm b \cosh \tau$$

$$\pm \ln \tau = \frac{z}{t}$$

$$z = \frac{v-u}{2} = \pm \frac{1}{2} (e^V - e^{-U}) = \pm b \sinh \tau$$

$$b^2 = t^2 - z^2$$

Killi-guon vekt. boostu

$$\xi = \frac{\partial}{\partial \tau} = z \frac{\partial}{\partial t} + t \frac{\partial}{\partial z} = v \frac{\partial}{\partial v} - u \frac{\partial}{\partial u} = \frac{\partial}{\partial V} + \frac{\partial}{\partial U}$$

metrika

$$g = -dt^2 + dz^2 + dx^2 + dy^2 = \begin{matrix} \text{R.L./F.P.} \\ \mp \end{matrix} b^2 d\tau^2 \pm db^2 + dx^2 + dy^2$$

$$= -\frac{1}{2} du dv + dx^2 + dy^2 = \frac{1}{2} s_u s_v b^2 dU \cdot dV + dx^2 + dy^2$$

$$\square \phi = \left[-\frac{\partial^2}{\partial t^2} + \frac{\partial^2}{\partial z^2} + \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right] \phi = \left[-4 \frac{\partial}{\partial u} \frac{\partial}{\partial v} + \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right] \phi \quad \tilde{\square} = [-\square + m^2]$$

