

Basics of calculus

- derivative of a function

one variable

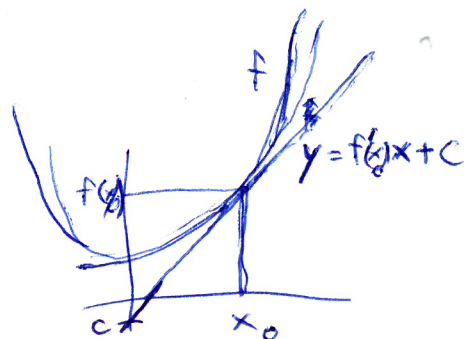
$$\left. \frac{df(x)}{dx} \right|_{x=x_0} = f'(x_0) \equiv \lim_{h \rightarrow 0} \frac{f(x_0+h) - f(x_0)}{h}$$

more variables - partial derivatives

$$\left. \frac{\partial f(x, y)}{\partial x} \right|_{(x_0, y_0)} = \lim_{h \rightarrow 0} \frac{f(x_0+h, y_0) - f(x_0, y_0)}{h}$$

keep y fixed

similarly for y



constant $c : f(x_0) = f'(x_0)x_0 + c$

$$c = f(x_0) - f'(x_0)x_0$$

$$\Rightarrow y = f(x_0) + f'(x_0)(x - x_0) + \left(\frac{1}{2} f''(x_0)(x - x_0)^2 + \dots \right)$$

first two terms of Taylor series

$$\lim_{h \rightarrow 0} \frac{f(x_0+h)g(x_0+h) - f(x_0)g(x_0)}{h}$$

$$= \lim_{h \rightarrow 0} \left(\frac{f(x_0+h) - f(x_0)}{h} \cdot g(x_0+h) \right) + \frac{f(x_0)(g(x_0+h) - g(x_0))}{h}$$

$$= f'(x_0)g(x_0) + f(x_0)g'(x_0)$$

- rules

$$(\alpha f + \beta g)' = \alpha f'(x) + \beta g'(x) \quad \text{linearity}$$

$$(f(x)g(x))' = f'(x)g(x) + f(x)g'(x) \quad \text{Leibnitz rule}$$

$$(f(g(x)))' = f'(g(x))g'(x) \quad \text{composition rule}$$

$$(f^{-1})'(y) = \frac{1}{f'(f^{-1}(y))} \quad \text{inverse function}$$

$$\leftarrow \text{from } \frac{d}{dy} \Big|_{f(f^{-1}(y))} = y$$

examples

$$(x^n)' = \lim_{h \rightarrow 0} \frac{(x+h)^n - x^n}{h} = nx^{n-1}$$

$$(e^x)' = e^x \quad \leftarrow \text{we need } \lim_{h \rightarrow 0} \frac{e^h - 1}{h} = 1$$

$$(\sin x)' = \cos x \quad \leftarrow \text{we need } \lim_{h \rightarrow 0} \frac{\sin h}{h} = 1, \quad \lim_{h \rightarrow 0} \frac{\cos h - 1}{h} = 0$$

- fundamental theorem of calculus

$$f \in C[a, b] \text{ and let } F(x) = \int_0^x f(t) dt \text{ on } [a, b]$$

then $F'(x) = f(x)$ (F is antiderivative of f)

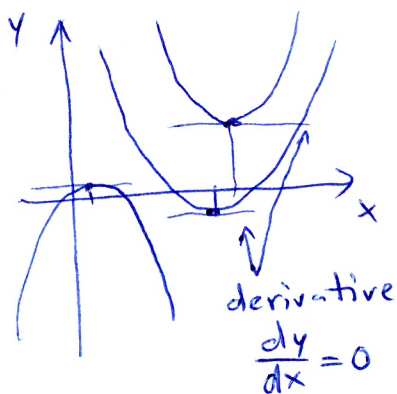
$$\Rightarrow \boxed{\int_a^b f(t) dt = F(b) - F(a)}$$

so we need to know the function $F(x)$ which has as its derivative the function $f(x)$ (not always in the closed form)

Examples on derivatives

1) Maxima and minima of functions

a) Find a derivative of $y(x) = ax^2 + bx + c$ and its maximum or minimum depending on parameters



$$\boxed{\frac{dy(x)}{dx} = 2ax + b \cdot 1 + 0}$$

$\frac{d(x^2)}{dx} = 2x$ $\frac{dx}{dx} = 1$ $\frac{dc}{dx} = 0$

maxima or minima are at x_m satisfying $\left. \frac{dy(x)}{dx} \right|_{x_m} = 2ax_m + b = 0$

or $\boxed{x_m = -\frac{b}{2a}}$

for $a \neq 0$ (otherwise it is a line!)

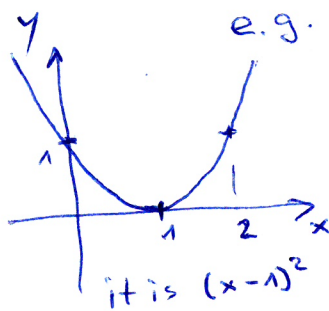
- how to determine whether it is a maximum or minimum?

From the sign of the second derivative!

If the second derivative is positive, then

the first derivative grows and we have a minimum!

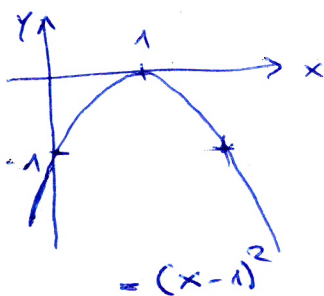
e.g. for $y(x) = x^2 - 2x + 1$ we set



$$\frac{dy(x)}{dx} = 2x - 2 \Rightarrow 2x_m = 2, x_m = 1 = -\frac{b}{2a}$$

$$\frac{d^2y(x)}{dx^2} = 2 > 0 \Rightarrow \text{minimum (in general it is } 2a)$$

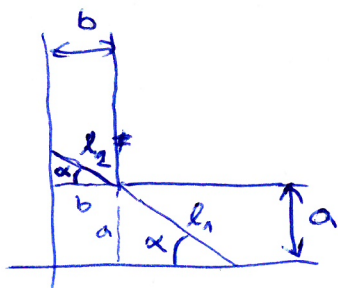
but for $y(x) = -x^2 + 2x - 1$ we set



$$\frac{dy(x)}{dx} = -2x + 2 \Rightarrow -2x_m = -2, x_m = 1 = -\frac{b}{2a}$$

$$\frac{d^2y(x)}{dx^2} = -2 < 0 \Rightarrow \text{maximum}$$

- b) Find the maximal length of a ladder you can carry horizontally in a corridor of L-shape



- we express the length as a function of the angle α :

$$L(\alpha) = l_1(\alpha) + l_2(\alpha) = \frac{a}{\sin \alpha} + \frac{b}{\cos \alpha}$$

$\frac{a}{l_1} = \sin \alpha \quad \frac{b}{l_2} = \cos \alpha$

- the minimum of this function corresponds to the maximal length of the ladder

- we calculate the derivative using

$$\frac{d}{d\alpha} \left(\frac{1}{f(\alpha)} \right) = - \frac{f'(\alpha)}{f^2(\alpha)}$$

and we get

$$\begin{aligned} \frac{dL(\alpha)}{d\alpha} &= a \left(- \frac{\cos \alpha}{\sin^2 \alpha} \right) + b \left(- \frac{(-\sin \alpha)}{\cos^2 \alpha} \right) = \\ &= \frac{b \sin \alpha}{\cos^2 \alpha} - \frac{a \cos \alpha}{\sin^2 \alpha} = \frac{b \sin^3 \alpha - a \cos^3 \alpha}{\cos^2 \alpha \sin^2 \alpha} \end{aligned}$$

thus α_m (where minimum is) is given by

$$b \sin^3 \alpha_m - a \cos^3 \alpha_m = 0$$

$$\text{or } \boxed{\tan \alpha_m = \sqrt[3]{\frac{a}{b}}}$$

- as one can expect, for $a=b$ we get

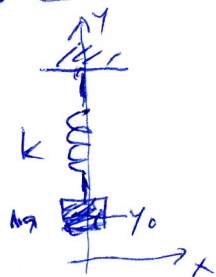
$$\alpha_m = \arctan 1 = \frac{\pi}{4} = 45^\circ$$

c)

Examples on derivatives

2) Checking that a certain "equation of motion" (description of a trajectory) is a solution of Newton's second law

a) linear harmonic oscillator



- you can find that oscillations of a mass m on a spring with the spring constant k are given by

$$y(t) = y_0 + A \sin \omega(t - t_0) \quad \text{where } \omega = \sqrt{\frac{k}{m}}$$

- check that it is a general solution of Newton's second law (in y -direction only)

$$m \cdot a_y = m \frac{d^2 y(t)}{dt^2} = F_y = -k(y(t) - y_0)$$

$$\frac{dy(t)}{dt} = 0 + A[\cos \omega(t - t_0)] \cdot \omega \quad \leftarrow \frac{d\omega(t - t_0)}{dt} = \omega$$

$$\frac{d^2 y(t)}{dt^2} = -A\omega^2 \sin \omega(t - t_0) \quad \text{thus}$$

$$m[-A\omega^2 \sin \omega(t - t_0)] = -k A \sin \omega(t - t_0) \Rightarrow \omega^2 = \frac{k}{m} \quad \checkmark$$

b) damped harmonic oscillator for the frictional force

$$F_f = -c v$$

↑
viscous damping coefficient

$$F = -k(y(t) - y_0) - c \frac{dy(t)}{dt}$$

- now the solution is