

```

> restart;
> with( Physics );
[ `*`, ` `, Annihilation, AntiCommutator, Antisymmetrize, Bra, Bracket, Check, Christoffel,
Coefficients, Commutator, Coordinates, Creation, D_, Dagger, Define, Dgamma, Einstein,
Expand, ExteriorDerivative, FeynmanDiagrams, Fundiff, Geodesics, GrassmannParity,
Gtaylor, Intc, Inverse, Ket, KillingVectors, δ, LeviCivita, Library, LieBracket, LieDerivative,
Normal, Parameters, PerformOnAnticommutativeSystem, Projector, Psigma, Ricci,
Riemann, Setup, Simplify, SpaceTimeVector, SubstituteTensorIndices,
SumOverRepeatedIndices, Symmetrize, TensorArray, ToFieldComponents, ToSuperfields,
Trace, TransformCoordinates, Vectors, Weyl, `^`, dAlembertian, d_, diff, g_ ]

```

```

> Setup( dimension=2 );
The dimension and signature of the tensor space are set to: [2, -]
[ dimension = 2 ] (2)

```

```

> Coordinates( X=[z,phi],W=[u,psi] );
Default differentiation variables for d_, D_ and dAlembertian are: { }
Systems of spacetime Coordinates are: { W=(u,ψ), X=(z,φ) }
{ W, X } (3)

```

```

> Setup(mathematicalnotation = true);
[ mathematicalnotation = true ] (4)

```

```

> Setup( metric=(1+z^2/(1+z^2))*d_(z)^2+(1+z^2)*d_(phi)^2 );
[ metric =  $\left\{ (1, 1) = 1 + \frac{z^2}{z^2 + 1}, (2, 2) = z^2 + 1 \right\} \right] (5)$ 
```

```

> deq:=Geodesics();
deq := 
$$\begin{aligned} \frac{d^2}{d\tau^2} z(\tau) &= \frac{z(\tau) (z(\tau)^2 + 1)^2 \left( \frac{d}{d\tau} \phi(\tau) \right)^2 - z(\tau) \left( \frac{d}{d\tau} z(\tau) \right)^2}{2 z(\tau)^4 + 3 z(\tau)^2 + 1}, \frac{d^2}{d\tau^2} \phi(\tau) = \\ &- \frac{2 z(\tau) \left( \frac{d}{d\tau} z(\tau) \right) \left( \frac{d}{d\tau} \phi(\tau) \right)}{z(\tau)^2 + 1} \end{aligned} (6)$$


```

```

> #dsolve( deq, [z(tau),phi(tau)] );

```

```

> metric2 := TransformCoordinates( [z=sinh(u),phi=psi] , g_[mu, nu], [u,psi] );
metric2 := 
$$\begin{bmatrix} 2 \cosh(u)^2 - 1 & 0 \\ 0 & \cosh(u)^2 \end{bmatrix} (7)$$

> restart;
with( Physics );

```

```

Setup( dimension=2 );
Setup(mathematicalnotation = true);
Coordinates( W = [u,psi] );
Setup( metric=(2*cosh(u)^2-1)*d_(u)^2+cosh(u)^2*d_(psi)^2 );

```

```
[`*', `; Annihilation, AntiCommutator, Antisymmetrize, Bra, Bracket, Check, Christoffel,
Coefficients, Commutator, Coordinates, Creation, D_, Dagger, Define, Dgamma, Einstein,
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SumOverRepeatedIndices, Symmetrize, TensorArray, ToFieldComponents, ToSuperfields,
Trace, TransformCoordinates, Vectors, Weyl, `^, dAlembertian, d_, diff, g_]
```

The dimension and signature of the tensor space are set to: [2, -]

[*dimension* = 2 ]

[mathematicalnotation = true]

*Default differentiation variables for d\_ , D\_ and dAlembertian are: { W=( u, \psi ) }*

*Systems of spacetime Coordinates are:  $\{W = (u, \psi)\}$*

{\$W\$}

[*metric* = { (1, 1) =  $2 \cosh(u)^2 - 1$ , (2, 2) =  $\cosh(u)^2$  } ]

(8)

```
> Simplify( Geodesics() );
```

$$\left[ \frac{d^2}{d\tau^2} u(\tau) = -\frac{2 \cosh(u(\tau)) \left( \left( \frac{d}{d\tau} u(\tau) \right)^2 - \frac{\left( \frac{d}{d\tau} \psi(\tau) \right)^2}{2} \right) \sinh(u(\tau))}{1 + 2 \sinh(u(\tau))^2}, \frac{d^2}{d\tau^2} \psi(\tau) \right. \\ \left. = -\frac{2 \sinh(u(\tau)) \left( \frac{d}{d\tau} u(\tau) \right) \left( \frac{d}{d\tau} \psi(\tau) \right)}{\cosh(u(\tau))} \right] \quad (9)$$

```
=> dsolve(%,[u(tau), psi(tau)]);
```

$$\left[ \begin{array}{l} u(\tau) = RootOf \\ \end{array} \right] \left( -\sqrt{2} \right) \quad (10)$$



$$\left.\left. \quad\quad\quad\right.^{1/2}\right)\mathrm{d}\tau+_{\_CI}\Big\}\Big]$$